

# Hints for Hw of Chapter 9.

Math 463/663 ①

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Compute:

$$9.2. \quad \frac{\partial f}{\partial x_1}, \quad \frac{\partial f}{\partial x_2}, \quad \frac{\partial^2 f}{\partial x_1^2}, \quad \frac{\partial^2 f}{\partial x_2^2}, \quad \frac{\partial^2 f}{\partial x_1 \partial x_2}.$$

$$f(\mathbf{0} + \vec{u}) = f(\mathbf{0}) + \left( \frac{\partial f}{\partial x_1} f(\mathbf{0}) \cdot u_1 + \frac{\partial f}{\partial x_2} f(\mathbf{0}) \cdot u_2 \right)$$

$$\vec{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}.$$

$$+ \left( \frac{\partial^2 f}{\partial x_1^2} f(\mathbf{0}) u_1^2 + \frac{\partial^2 f}{\partial x_2^2} f(\mathbf{0}) u_2^2 + 2 \frac{\partial^2 f}{\partial x_1 \partial x_2} f(\mathbf{0}) u_1 u_2 \right)$$

$$+ r_2(\mathbf{0}, \vec{u}).$$

$$9.3. \quad \vec{y}(\vec{x}) = \vec{g}(\vec{f}(\vec{x}))$$

$$\frac{\partial \vec{g}}{\partial \vec{f}^T} = \begin{bmatrix} -\frac{f_2}{g_1^2} & \frac{1}{g_1} \\ f_2 & f_1 \end{bmatrix}$$

$$\vec{f} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix}$$

$$\frac{\partial \vec{f}}{\partial \vec{x}^T} = \begin{bmatrix} 2x_1 & 2x_2 & 2x_3 \\ 2 & -1 & -1 \end{bmatrix}$$

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$\frac{\partial \vec{y}}{\partial \vec{x}^T} = \frac{\partial \vec{y}}{\partial \vec{f}^T} \frac{\partial \vec{f}}{\partial \vec{x}^T} = \dots$$

$$9.4. \quad d f(\vec{x}) = e^{-\frac{1}{2} \vec{x}^T A \vec{x}} d\left(-\frac{1}{2} \vec{x}^T A \vec{x}\right)$$

(2)

$$= \dots$$

$$\vdots$$

$$= -f(\vec{x}) \cdot \vec{x}^T A d\vec{x}$$

$$\Rightarrow \frac{\partial}{\partial \vec{x}^T} f(\vec{x}) = \dots$$

$$9.5. \quad d f(\vec{x}) = \frac{(\vec{x}^T B \vec{x}) d(\vec{x}^T A \vec{x}) - (\vec{x}^T A \vec{x}) d(\vec{x}^T B \vec{x})}{(\vec{x}^T B \vec{x})^2}$$

$$= \dots$$

$$9.6. \quad d(\vec{x} \vec{x}^T) = (d\vec{x}) \vec{x}^T + \vec{x} (d\vec{x})^T$$

$$\text{So } d \text{vec}(\vec{x} \vec{x}^T) = \text{vec}((d\vec{x}) \vec{x}^T) + \text{vec}(\vec{x} (d\vec{x})^T)$$

$$\stackrel{\text{Thm 8.9 (b)}}{=} \vec{x} \otimes d\vec{x} + d\vec{x} \otimes \vec{x}$$

$$\stackrel{\text{Thm 8.26 (c)}}{=} \vec{x} \otimes d\vec{x} + K_{mm}(\vec{x} \otimes d\vec{x})$$

$$\stackrel{\text{Ex 8.4 (b)}}{=} (\vec{x} \otimes I_m) d\vec{x} + K_{mm}(\vec{x} \otimes I_m) d\vec{x}$$

$$= (I_m^2 + K_{mm})(\vec{x} \otimes I_m) d\vec{x}$$

$$\text{So } \frac{\partial f}{\partial \bar{x}^T} \text{vec}(\bar{x}\bar{x}^T) = \dots$$

(3)

$$\begin{aligned} \text{9.7 (a)} \quad d\text{tr}(AX) &= \text{tr}(A dx) \\ &= \text{vec}(A^T)^T \text{vec}(dx) \\ &= \text{vec}(A^T)^T d\text{vec}(x) \end{aligned}$$

$$\text{So } \frac{\partial \text{tr}(AX)}{\partial \text{vec}(x)^T} = \dots$$

$$\begin{aligned} \text{(b)} \quad d\text{tr}(AXBX) &= \text{tr}(A(dx)BX) + \text{tr}(AXB dx) \\ &= \text{tr}(BXA(dx)) + \text{tr}(AXB dx) \\ &= \text{vec}([BXA]^T + [AXB]^T)^T \text{vec}(dx) \\ &= \dots \end{aligned}$$

$$\frac{\partial \text{tr}(AXBX)}{\partial \text{vec}(x)^T} = \dots$$

$$\text{9.8. (a)} \quad d|x^2| = d|x|^2 = 2|x|d|x| \stackrel{\text{Thm 9.1(c)}}{=} \dots \quad \left( \frac{\partial |x|^2}{\partial \text{vec}(x)^T} = \dots \right)$$

$$\text{(b)} \quad d\text{tr}(AX^{-1}) = \text{tr}(A dX^{-1}) \stackrel{\text{Thm 9.2}}{=} \dots \quad \left( \frac{\partial \text{tr}(AX^{-1})}{\partial \text{vec}(x)^T} = \dots \right)$$

$$(c) \quad d \vec{a}^T X^{-1} \vec{a} = \vec{a}^T d X^{-1} \vec{a}$$

(4)

Thm 9.2

use Thm 8.11, i.e.,

$$\text{vec}(ABC) = (C^T \otimes A) \text{vec}(B)$$

$$\frac{d \vec{a}^T X^{-1} \vec{a}}{d \text{vec}(X)^T} = \dots$$

9.9. By Corollary 9.11 on p. 397

$$d \log |X^T A X| = \text{tr} \left( (X^T A X)^{-1} d(X^T A X) \right)$$

⋮

$$\frac{d \log |X^T A X|}{d \text{vec}(X)^T} = \dots$$

9.10. By Thm 9.1(c). (here  $X^T X$  is nonsingular)

$$d(X^T X) = |X^T X| \text{tr} \left( (X^T X)^{-1} d(X^T X) \right)$$

=  
⋮

$$\frac{d |X^T X|}{d \text{vec}(X)^T} = \dots$$

9.12.

⑤

$$(a) \quad d \cdot \text{vec}(AxB) = \text{vec}(A(dx)B)$$

$$\stackrel{\text{Thm 8.11}}{=} (B^T \otimes A) \text{vec}(dx)$$

$$\frac{\partial \text{vec}(AxB)}{\partial \text{vec}(x)^T} = \dots$$

$$(b) \quad d \text{vec}(AX^{-1}B) = \text{vec}(A dX^{-1}B) \stackrel{\text{Thm 9.2}}{=} \text{vec}(\dots)$$

$$\frac{\partial \text{vec}(AX^{-1}B)}{\partial \text{vec}(x)^T} = \dots$$