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LINEAR ALGEBRA with Applications

Open Edition



Adapted for

Emory University

Math 221

Linear Algebra

Sections 1 & 2

Lectured and adapted by

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Course page

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Supplementary Exercises for Chapter 5

Exercise 5.1 In each case either show that the statement is true or give an example showing that it is false. Throughout, \mathbf{x} , \mathbf{y} , \mathbf{z} , \mathbf{x}_1 , \mathbf{x}_2 , ..., \mathbf{x}_n denote vectors in \mathbb{R}^n .

- a. If U is a subspace of \mathbb{R}^n and $\mathbf{x} + \mathbf{y}$ is in U , then \mathbf{x} and \mathbf{y} are both in U .
 - b. If U is a subspace of \mathbb{R}^n and $r\mathbf{x}$ is in U , then \mathbf{x} is in U .
 - c. If U is a nonempty set and $s\mathbf{x} + t\mathbf{y}$ is in U for any s and t whenever \mathbf{x} and \mathbf{y} are in U , then U is a subspace.
 - d. If U is a subspace of \mathbb{R}^n and \mathbf{x} is in U , then $-\mathbf{x}$ is in U .
 - e. If $\{\mathbf{x}, \mathbf{y}\}$ is independent, then $\{\mathbf{x}, \mathbf{y}, \mathbf{x} + \mathbf{y}\}$ is independent.
 - f. If $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ is independent, then $\{\mathbf{x}, \mathbf{y}\}$ is independent.
 - g. If $\{\mathbf{x}, \mathbf{y}\}$ is not independent, then $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ is not independent.
 - h. If all of $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ are nonzero, then $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ is independent.
 - i. If one of $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ is zero, then $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ is not independent.
 - j. If $a\mathbf{x} + b\mathbf{y} + c\mathbf{z} = \mathbf{0}$ where a, b , and c are in \mathbb{R} , then $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ is independent.
 - k. If $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ is independent, then $a\mathbf{x} + b\mathbf{y} + c\mathbf{z} = \mathbf{0}$ for some a, b , and c in \mathbb{R} .
 - l. If $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ is not independent, then $t_1\mathbf{x}_1 + t_2\mathbf{x}_2 + \dots + t_n\mathbf{x}_n = \mathbf{0}$ for t_i in \mathbb{R} not all zero.
 - m. If $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ is independent, then $t_1\mathbf{x}_1 + t_2\mathbf{x}_2 + \dots + t_n\mathbf{x}_n = \mathbf{0}$ for some t_i in \mathbb{R} .
 - n. Every set of four non-zero vectors in \mathbb{R}^4 is a basis.
 - o. No basis of \mathbb{R}^3 can contain a vector with a component 0 .
 - p. \mathbb{R}^3 has a basis of the form $\{\mathbf{x}, \mathbf{x} + \mathbf{y}, \mathbf{y}\}$ where \mathbf{x} and \mathbf{y} are vectors.
 - q. Every basis of \mathbb{R}^5 contains one column of I_5 .
 - r. Every nonempty subset of a basis of \mathbb{R}^3 is again a basis of \mathbb{R}^3 .
 - s. If $\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4\}$ and $\{\mathbf{y}_1, \mathbf{y}_2, \mathbf{y}_3, \mathbf{y}_4\}$ are bases of \mathbb{R}^4 , then $\{\mathbf{x}_1 + \mathbf{y}_1, \mathbf{x}_2 + \mathbf{y}_2, \mathbf{x}_3 + \mathbf{y}_3, \mathbf{x}_4 + \mathbf{y}_4\}$ is also a basis of \mathbb{R}^4 .
-
- b. F
 - d. T
 - f. T
 - h. F
 - j. F
 - l. T
 - n. F
 - p. F
 - r. F

