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LINEAR ALGEBRA with Applications

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Adapted for

Emory University

Math 221

Linear Algebra

Sections 1 & 2

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8.1 Orthogonal Complements and Projections

If $\{\mathbf{v}_1, \dots, \mathbf{v}_m\}$ is linearly independent in a general vector space, and if \mathbf{v}_{m+1} is not in $\text{span}\{\mathbf{v}_1, \dots, \mathbf{v}_m\}$, then $\{\mathbf{v}_1, \dots, \mathbf{v}_m, \mathbf{v}_{m+1}\}$ is independent (Lemma 6.4.1). Here is the analog for *orthogonal* sets in \mathbb{R}^n .

Lemma 8.1.1: Orthogonal Lemma

Let $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$ be an orthogonal set in \mathbb{R}^n . Given \mathbf{x} in \mathbb{R}^n , write

$$\mathbf{f}_{m+1} = \mathbf{x} - \frac{\mathbf{x} \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 - \frac{\mathbf{x} \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2 - \dots - \frac{\mathbf{x} \cdot \mathbf{f}_m}{\|\mathbf{f}_m\|^2} \mathbf{f}_m$$

Then:

1. $\mathbf{f}_{m+1} \cdot \mathbf{f}_k = 0$ for $k = 1, 2, \dots, m$.
2. If \mathbf{x} is not in $\text{span}\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$, then $\mathbf{f}_{m+1} \neq \mathbf{0}$ and $\{\mathbf{f}_1, \dots, \mathbf{f}_m, \mathbf{f}_{m+1}\}$ is an orthogonal set.

Proof. For convenience, write $t_i = (\mathbf{x} \cdot \mathbf{f}_i) / \|\mathbf{f}_i\|^2$ for each i . Given $1 \leq k \leq m$:

$$\begin{aligned} \mathbf{f}_{m+1} \cdot \mathbf{f}_k &= (\mathbf{x} - t_1 \mathbf{f}_1 - \dots - t_k \mathbf{f}_k - \dots - t_m \mathbf{f}_m) \cdot \mathbf{f}_k \\ &= \mathbf{x} \cdot \mathbf{f}_k - t_1 (\mathbf{f}_1 \cdot \mathbf{f}_k) - \dots - t_k (\mathbf{f}_k \cdot \mathbf{f}_k) - \dots - t_m (\mathbf{f}_m \cdot \mathbf{f}_k) \\ &= \mathbf{x} \cdot \mathbf{f}_k - t_k \|\mathbf{f}_k\|^2 \\ &= 0 \end{aligned}$$

This proves (1), and (2) follows because $\mathbf{f}_{m+1} \neq \mathbf{0}$ if \mathbf{x} is not in $\text{span}\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$. □

The orthogonal lemma has three important consequences for \mathbb{R}^n . The first is an extension for orthogonal sets of the fundamental fact that any independent set is part of a basis (Theorem 6.4.1).

Theorem 8.1.1

Let U be a subspace of \mathbb{R}^n .

1. Every orthogonal subset $\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$ in U is a subset of an orthogonal basis of U .
2. U has an orthogonal basis.

Proof.

1. If $\text{span}\{\mathbf{f}_1, \dots, \mathbf{f}_m\} = U$, it is *already* a basis. Otherwise, there exists \mathbf{x} in U outside $\text{span}\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$. If \mathbf{f}_{m+1} is as given in the orthogonal lemma, then \mathbf{f}_{m+1} is in U and $\{\mathbf{f}_1, \dots, \mathbf{f}_m, \mathbf{f}_{m+1}\}$ is orthogonal. If $\text{span}\{\mathbf{f}_1, \dots, \mathbf{f}_m, \mathbf{f}_{m+1}\} = U$, we are done. Otherwise,

the process continues to create larger and larger orthogonal subsets of U . They are all independent by Theorem 5.3.5, so we have a basis when we reach a subset containing $\dim U$ vectors.

2. If $U = \{\mathbf{0}\}$, the empty basis is orthogonal. Otherwise, if $\mathbf{f} \neq \mathbf{0}$ is in U , then $\{\mathbf{f}\}$ is orthogonal, so (2) follows from (1). \square

We can improve upon (2) of Theorem 8.1.1. In fact, the second consequence of the orthogonal lemma is a procedure by which *any* basis $\{\mathbf{x}_1, \dots, \mathbf{x}_m\}$ of a subspace U of \mathbb{R}^n can be systematically modified to yield an orthogonal basis $\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$ of U . The \mathbf{f}_i are constructed one at a time from the \mathbf{x}_i .

To start the process, take $\mathbf{f}_1 = \mathbf{x}_1$. Then \mathbf{x}_2 is not in $\text{span}\{\mathbf{f}_1\}$ because $\{\mathbf{x}_1, \mathbf{x}_2\}$ is independent, so take

$$\mathbf{f}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1$$

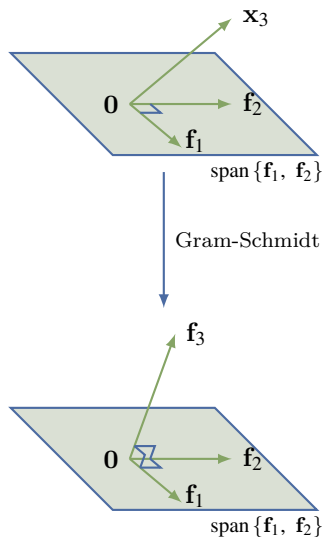
Thus $\{\mathbf{f}_1, \mathbf{f}_2\}$ is orthogonal by Lemma 8.1.1. Moreover, $\text{span}\{\mathbf{f}_1, \mathbf{f}_2\} = \text{span}\{\mathbf{x}_1, \mathbf{x}_2\}$ (verify), so \mathbf{x}_3 is not in $\text{span}\{\mathbf{f}_1, \mathbf{f}_2\}$. Hence $\{\mathbf{f}_1, \mathbf{f}_2, \mathbf{f}_3\}$ is orthogonal where

$$\mathbf{f}_3 = \mathbf{x}_3 - \frac{\mathbf{x}_3 \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2$$

Again, $\text{span}\{\mathbf{f}_1, \mathbf{f}_2, \mathbf{f}_3\} = \text{span}\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\}$, so \mathbf{x}_4 is not in $\text{span}\{\mathbf{f}_1, \mathbf{f}_2, \mathbf{f}_3\}$ and the process continues. At the m th iteration we construct an orthogonal set $\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$ such that

$$\text{span}\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\} = \text{span}\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_m\} = U$$

Hence $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$ is the desired orthogonal basis of U . The procedure can be summarized as follows.



Theorem 8.1.2: Gram-Schmidt Orthogonalization Algorithm¹

If $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_m\}$ is any basis of a subspace U of \mathbb{R}^n , construct $\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m$ in U successively as follows:

$$\begin{aligned} \mathbf{f}_1 &= \mathbf{x}_1 \\ \mathbf{f}_2 &= \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 \\ \mathbf{f}_3 &= \mathbf{x}_3 - \frac{\mathbf{x}_3 \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2 \\ &\vdots \\ \mathbf{f}_k &= \mathbf{x}_k - \frac{\mathbf{x}_k \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 - \frac{\mathbf{x}_k \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2 - \dots - \frac{\mathbf{x}_k \cdot \mathbf{f}_{k-1}}{\|\mathbf{f}_{k-1}\|^2} \mathbf{f}_{k-1} \end{aligned}$$

for each $k = 2, 3, \dots, m$. Then

1. $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$ is an orthogonal basis of U .
2. $\text{span}\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_k\} = \text{span}\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k\}$ for each $k = 1, 2, \dots, m$.

The process (for $k = 3$) is depicted in the diagrams. Of course, the algorithm converts any basis of \mathbb{R}^n itself into an orthogonal basis.

Example 8.1.1

Find an orthogonal basis of the row space of $A = \begin{bmatrix} 1 & 1 & -1 & -1 \\ 3 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{bmatrix}$.

Solution. Let $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3$ denote the rows of A and observe that $\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\}$ is linearly independent. Take $\mathbf{f}_1 = \mathbf{x}_1$. The algorithm gives

$$\mathbf{f}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 = (3, 2, 0, 1) - \frac{4}{4}(1, 1, -1, -1) = (2, 1, 1, 2)$$

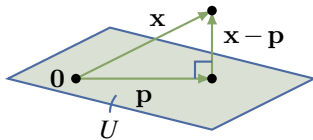
$$\mathbf{f}_3 = \mathbf{x}_3 - \frac{\mathbf{x}_3 \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2 = \mathbf{x}_3 - \frac{0}{4} \mathbf{f}_1 - \frac{3}{10} \mathbf{f}_2 = \frac{1}{10}(4, -3, 7, -6)$$

Hence $\{(1, 1, -1, -1), (2, 1, 1, 2), \frac{1}{10}(4, -3, 7, -6)\}$ is the orthogonal basis provided by the algorithm. In hand calculations it may be convenient to eliminate fractions (see the Remark below), so $\{(1, 1, -1, -1), (2, 1, 1, 2), (4, -3, 7, -6)\}$ is also an orthogonal basis for row A .

¹Erhardt Schmidt (1876–1959) was a German mathematician who studied under the great David Hilbert and later developed the theory of Hilbert spaces. He first described the present algorithm in 1907. Jørgen Pederson Gram (1850–1916) was a Danish actuary.

Remark

Observe that the vector $\frac{\mathbf{x} \cdot \mathbf{f}_i}{\|\mathbf{f}_i\|^2} \mathbf{f}_i$ is unchanged if a nonzero scalar multiple of \mathbf{f}_i is used in place of \mathbf{f}_i . Hence, if a newly constructed \mathbf{f}_i is multiplied by a nonzero scalar at some stage of the Gram-Schmidt algorithm, the subsequent \mathbf{f}_i s will be unchanged. This is useful in actual calculations.

Projections

Suppose a point \mathbf{x} and a plane U through the origin in \mathbb{R}^3 are given, and we want to find the point \mathbf{p} in the plane that is closest to \mathbf{x} . Our geometric intuition assures us that such a point \mathbf{p} exists. In fact (see the diagram), \mathbf{p} must be chosen in such a way that $\mathbf{x} - \mathbf{p}$ is *perpendicular* to the plane.

Now we make two observations: first, the plane U is a *subspace* of \mathbb{R}^3 (because U contains the origin); and second, that the condition that $\mathbf{x} - \mathbf{p}$ is perpendicular to the plane U means that $\mathbf{x} - \mathbf{p}$ is *orthogonal* to every vector in U . In these terms the whole discussion makes sense in \mathbb{R}^n . Furthermore, the orthogonal lemma provides exactly what is needed to find \mathbf{p} in this more general setting.

Definition 8.1 Orthogonal Complement of a Subspace of \mathbb{R}^n

If U is a subspace of \mathbb{R}^n , define the **orthogonal complement** U^\perp of U (pronounced “ U -perp”) by

$$U^\perp = \{\mathbf{x} \text{ in } \mathbb{R}^n \mid \mathbf{x} \cdot \mathbf{y} = 0 \text{ for all } \mathbf{y} \text{ in } U\}$$

The following lemma collects some useful properties of the orthogonal complement; the proof of (1) and (2) is left as Exercise 8.1.6.

Lemma 8.1.2

Let U be a subspace of \mathbb{R}^n .

1. U^\perp is a subspace of \mathbb{R}^n .
2. $\{\mathbf{0}\}^\perp = \mathbb{R}^n$ and $(\mathbb{R}^n)^\perp = \{\mathbf{0}\}$.
3. If $U = \text{span}\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k\}$, then $U^\perp = \{\mathbf{x} \text{ in } \mathbb{R}^n \mid \mathbf{x} \cdot \mathbf{x}_i = 0 \text{ for } i = 1, 2, \dots, k\}$.

Proof.

3. Let $U = \text{span}\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k\}$; we must show that $U^\perp = \{\mathbf{x} \mid \mathbf{x} \cdot \mathbf{x}_i = 0 \text{ for each } i\}$. If \mathbf{x} is in U^\perp then $\mathbf{x} \cdot \mathbf{x}_i = 0$ for all i because each \mathbf{x}_i is in U . Conversely, suppose that $\mathbf{x} \cdot \mathbf{x}_i = 0$ for all i ; we must show that \mathbf{x} is in U^\perp , that is, $\mathbf{x} \cdot \mathbf{y} = 0$ for each \mathbf{y} in U . Write $\mathbf{y} = r_1\mathbf{x}_1 + r_2\mathbf{x}_2 + \dots + r_k\mathbf{x}_k$, where each r_i is in \mathbb{R} . Then, using Theorem 5.3.1,

$$\mathbf{x} \cdot \mathbf{y} = r_1(\mathbf{x} \cdot \mathbf{x}_1) + r_2(\mathbf{x} \cdot \mathbf{x}_2) + \dots + r_k(\mathbf{x} \cdot \mathbf{x}_k) = r_1\mathbf{0} + r_2\mathbf{0} + \dots + r_k\mathbf{0} = 0$$

as required. □

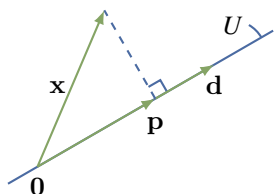
Example 8.1.2

Find U^\perp if $U = \text{span}\{(1, -1, 2, 0), (1, 0, -2, 3)\}$ in \mathbb{R}^4 .

Solution. By Lemma 8.1.2, $\mathbf{x} = (x, y, z, w)$ is in U^\perp if and only if it is orthogonal to both $(1, -1, 2, 0)$ and $(1, 0, -2, 3)$; that is,

$$\begin{aligned}x - y + 2z &= 0 \\x - 2z + 3w &= 0\end{aligned}$$

Gaussian elimination gives $U^\perp = \text{span}\{(2, 4, 1, 0), (3, 3, 0, -1)\}$.



Now consider vectors \mathbf{x} and $\mathbf{d} \neq \mathbf{0}$ in \mathbb{R}^3 . The projection $\mathbf{p} = \text{proj}_{\mathbf{d}} \mathbf{x}$ of \mathbf{x} on \mathbf{d} was defined in Section 4.2 as in the diagram.

The following formula for \mathbf{p} was derived in Theorem 4.2.4

$$\mathbf{p} = \text{proj}_{\mathbf{d}} \mathbf{x} = \left(\frac{\mathbf{x} \cdot \mathbf{d}}{\|\mathbf{d}\|^2} \right) \mathbf{d}$$

where it is shown that $\mathbf{x} - \mathbf{p}$ is orthogonal to \mathbf{d} . Now observe that the line $U = \mathbb{R}\mathbf{d} = \{t\mathbf{d} \mid t \in \mathbb{R}\}$ is a subspace of \mathbb{R}^3 , that $\{\mathbf{d}\}$ is an orthogonal basis of U , and that $\mathbf{p} \in U$ and $\mathbf{x} - \mathbf{p} \in U^\perp$ (by Theorem 4.2.4).

In this form, this makes sense for any vector \mathbf{x} in \mathbb{R}^n and any subspace U of \mathbb{R}^n , so we generalize it as follows. If $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$ is an orthogonal basis of U , we define the projection \mathbf{p} of \mathbf{x} on U by the formula

$$\mathbf{p} = \left(\frac{\mathbf{x} \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \right) \mathbf{f}_1 + \left(\frac{\mathbf{x} \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \right) \mathbf{f}_2 + \cdots + \left(\frac{\mathbf{x} \cdot \mathbf{f}_m}{\|\mathbf{f}_m\|^2} \right) \mathbf{f}_m \quad (8.1)$$

Then $\mathbf{p} \in U$ and (by the orthogonal lemma) $\mathbf{x} - \mathbf{p} \in U^\perp$, so it looks like we have a generalization of Theorem 4.2.4.

However there is a potential problem: the formula (8.1) for \mathbf{p} must be shown to be independent of the choice of the orthogonal basis $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$. To verify this, suppose that $\{\mathbf{f}'_1, \mathbf{f}'_2, \dots, \mathbf{f}'_m\}$ is another orthogonal basis of U , and write

$$\mathbf{p}' = \left(\frac{\mathbf{x} \cdot \mathbf{f}'_1}{\|\mathbf{f}'_1\|^2} \right) \mathbf{f}'_1 + \left(\frac{\mathbf{x} \cdot \mathbf{f}'_2}{\|\mathbf{f}'_2\|^2} \right) \mathbf{f}'_2 + \cdots + \left(\frac{\mathbf{x} \cdot \mathbf{f}'_m}{\|\mathbf{f}'_m\|^2} \right) \mathbf{f}'_m$$

As before, $\mathbf{p}' \in U$ and $\mathbf{x} - \mathbf{p}' \in U^\perp$, and we must show that $\mathbf{p}' = \mathbf{p}$. To see this, write the vector $\mathbf{p} - \mathbf{p}'$ as follows:

$$\mathbf{p} - \mathbf{p}' = (\mathbf{x} - \mathbf{p}') - (\mathbf{x} - \mathbf{p})$$

This vector is in U (because \mathbf{p} and \mathbf{p}' are in U) and it is in U^\perp (because $\mathbf{x} - \mathbf{p}'$ and $\mathbf{x} - \mathbf{p}$ are in U^\perp), and so it must be zero (it is orthogonal to itself!). This means $\mathbf{p}' = \mathbf{p}$ as desired.

Hence, the vector \mathbf{p} in equation (8.1) depends only on \mathbf{x} and the subspace U , and *not* on the choice of orthogonal basis $\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$ of U used to compute it. Thus, we are entitled to make the following definition:

Definition 8.2 Projection onto a Subspace of \mathbb{R}^n

Let U be a subspace of \mathbb{R}^n with orthogonal basis $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$. If \mathbf{x} is in \mathbb{R}^n , the vector

$$\text{proj}_U \mathbf{x} = \frac{\mathbf{x} \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 + \frac{\mathbf{x} \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2 + \cdots + \frac{\mathbf{x} \cdot \mathbf{f}_m}{\|\mathbf{f}_m\|^2} \mathbf{f}_m$$

is called the **orthogonal projection** of \mathbf{x} on U . For the zero subspace $U = \{\mathbf{0}\}$, we define

$$\text{proj}_{\{\mathbf{0}\}} \mathbf{x} = \mathbf{0}$$

The preceding discussion proves (1) of the following theorem.

Theorem 8.1.3: Projection Theorem

If U is a subspace of \mathbb{R}^n and \mathbf{x} is in \mathbb{R}^n , write $\mathbf{p} = \text{proj}_U \mathbf{x}$. Then:

1. \mathbf{p} is in U and $\mathbf{x} - \mathbf{p}$ is in U^\perp .
2. \mathbf{p} is the vector in U closest to \mathbf{x} in the sense that

$$\|\mathbf{x} - \mathbf{p}\| < \|\mathbf{x} - \mathbf{y}\| \quad \text{for all } \mathbf{y} \in U, \mathbf{y} \neq \mathbf{p}$$

Proof.

1. This is proved in the preceding discussion (it is clear if $U = \{\mathbf{0}\}$).
2. Write $\mathbf{x} - \mathbf{y} = (\mathbf{x} - \mathbf{p}) + (\mathbf{p} - \mathbf{y})$. Then $\mathbf{p} - \mathbf{y}$ is in U and so is orthogonal to $\mathbf{x} - \mathbf{p}$ by (1). Hence, the Pythagorean theorem gives

$$\|\mathbf{x} - \mathbf{y}\|^2 = \|\mathbf{x} - \mathbf{p}\|^2 + \|\mathbf{p} - \mathbf{y}\|^2 > \|\mathbf{x} - \mathbf{p}\|^2$$

because $\mathbf{p} - \mathbf{y} \neq \mathbf{0}$. This gives (2). □

Example 8.1.3

Let $U = \text{span}\{\mathbf{x}_1, \mathbf{x}_2\}$ in \mathbb{R}^4 where $\mathbf{x}_1 = (1, 1, 0, 1)$ and $\mathbf{x}_2 = (0, 1, 1, 2)$. If $\mathbf{x} = (3, -1, 0, 2)$, find the vector in U closest to \mathbf{x} and express \mathbf{x} as the sum of a vector in U and a vector orthogonal to U .

Solution. $\{\mathbf{x}_1, \mathbf{x}_2\}$ is independent but not orthogonal. The Gram-Schmidt process gives an orthogonal basis $\{\mathbf{f}_1, \mathbf{f}_2\}$ of U where $\mathbf{f}_1 = \mathbf{x}_1 = (1, 1, 0, 1)$ and

$$\mathbf{f}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 = \mathbf{x}_2 - \frac{3}{3} \mathbf{f}_1 = (-1, 0, 1, 1)$$

Hence, we can compute the projection using $\{\mathbf{f}_1, \mathbf{f}_2\}$:

$$\mathbf{p} = \text{proj}_U \mathbf{x} = \frac{\mathbf{x} \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 + \frac{\mathbf{x} \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2 = \frac{4}{3} \mathbf{f}_1 + \frac{-1}{3} \mathbf{f}_2 = \frac{1}{3} \begin{bmatrix} 5 & 4 & -1 & 3 \end{bmatrix}$$

Thus, \mathbf{p} is the vector in U closest to \mathbf{x} , and $\mathbf{x} - \mathbf{p} = \frac{1}{3}(4, -7, 1, 3)$ is orthogonal to every vector in U . (This can be verified by checking that it is orthogonal to the generators \mathbf{x}_1 and \mathbf{x}_2 of U .) The required decomposition of \mathbf{x} is thus

$$\mathbf{x} = \mathbf{p} + (\mathbf{x} - \mathbf{p}) = \frac{1}{3}(5, 4, -1, 3) + \frac{1}{3}(4, -7, 1, 3)$$

Example 8.1.4

Find the point in the plane with equation $2x + y - z = 0$ that is closest to the point $(2, -1, -3)$.

Solution. We write \mathbb{R}^3 as rows. The plane is the subspace U whose points (x, y, z) satisfy $z = 2x + y$. Hence

$$U = \{(s, t, 2s + t) \mid s, t \text{ in } \mathbb{R}\} = \text{span}\{(0, 1, 1), (1, 0, 2)\}$$

The Gram-Schmidt process produces an orthogonal basis $\{\mathbf{f}_1, \mathbf{f}_2\}$ of U where $\mathbf{f}_1 = (0, 1, 1)$ and $\mathbf{f}_2 = (1, -1, 1)$. Hence, the vector in U closest to $\mathbf{x} = (2, -1, -3)$ is

$$\text{proj}_U \mathbf{x} = \frac{\mathbf{x} \cdot \mathbf{f}_1}{\|\mathbf{f}_1\|^2} \mathbf{f}_1 + \frac{\mathbf{x} \cdot \mathbf{f}_2}{\|\mathbf{f}_2\|^2} \mathbf{f}_2 = -2\mathbf{f}_1 + 0\mathbf{f}_2 = (0, -2, -2)$$

Thus, the point in U closest to $(2, -1, -3)$ is $(0, -2, -2)$.

The next theorem shows that projection on a subspace of \mathbb{R}^n is actually a linear operator $\mathbb{R}^n \rightarrow \mathbb{R}^n$.

Theorem 8.1.4

Let U be a fixed subspace of \mathbb{R}^n . If we define $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ by

$$T(\mathbf{x}) = \text{proj}_U \mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n$$

1. T is a linear operator.
2. $\text{im } T = U$ and $\ker T = U^\perp$.
3. $\dim U + \dim U^\perp = n$.

Proof. If $U = \{\mathbf{0}\}$, then $U^\perp = \mathbb{R}^n$, and so $T(\mathbf{x}) = \text{proj}_{\{\mathbf{0}\}} \mathbf{x} = \mathbf{0}$ for all \mathbf{x} . Thus $T = \mathbf{0}$ is the zero (linear) operator, so (1), (2), and (3) hold. Hence assume that $U \neq \{\mathbf{0}\}$.

1. If $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$ is an orthonormal basis of U , then

$$T(\mathbf{x}) = (\mathbf{x} \cdot \mathbf{f}_1)\mathbf{f}_1 + (\mathbf{x} \cdot \mathbf{f}_2)\mathbf{f}_2 + \cdots + (\mathbf{x} \cdot \mathbf{f}_m)\mathbf{f}_m \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n \quad (8.2)$$

by the definition of the projection. Thus T is linear because

$$(\mathbf{x} + \mathbf{y}) \cdot \mathbf{f}_i = \mathbf{x} \cdot \mathbf{f}_i + \mathbf{y} \cdot \mathbf{f}_i \quad \text{and} \quad (r\mathbf{x}) \cdot \mathbf{f}_i = r(\mathbf{x} \cdot \mathbf{f}_i) \quad \text{for each } i$$

2. We have $\text{im } T \subseteq U$ by (8.2) because each \mathbf{f}_i is in U . But if \mathbf{x} is in U , then $\mathbf{x} = T(\mathbf{x})$ by (8.2) and the expansion theorem applied to the space U . This shows that $U \subseteq \text{im } T$, so $\text{im } T = U$. Now suppose that \mathbf{x} is in U^\perp . Then $\mathbf{x} \cdot \mathbf{f}_i = 0$ for each i (again because each \mathbf{f}_i is in U) so \mathbf{x} is in $\ker T$ by (8.2). Hence $U^\perp \subseteq \ker T$. On the other hand, Theorem 8.1.3 shows that $\mathbf{x} - T(\mathbf{x})$ is in U^\perp for all \mathbf{x} in \mathbb{R}^n , and it follows that $\ker T \subseteq U^\perp$. Hence $\ker T = U^\perp$, proving (2).
3. This follows from (1), (2), and the dimension theorem (Theorem 7.2.4). □

Exercises for 8.1

Exercise 8.1.1 In each case, use the Gram-Schmidt algorithm to convert the given basis B of V into an orthogonal basis.

- a. $V = \mathbb{R}^2$, $B = \{(1, -1), (2, 1)\}$
 b. $V = \mathbb{R}^2$, $B = \{(2, 1), (1, 2)\}$
 c. $V = \mathbb{R}^3$, $B = \{(1, -1, 1), (1, 0, 1), (1, 1, 2)\}$
 d. $V = \mathbb{R}^3$, $B = \{(0, 1, 1), (1, 1, 1), (1, -2, 2)\}$

- b. $\{(2, 1), \frac{3}{5}(-1, 2)\}$
 d. $\{(0, 1, 1), (1, 0, 0), (0, -2, 2)\}$

Exercise 8.1.2 In each case, write \mathbf{x} as the sum of a vector in U and a vector in U^\perp .

- a. $\mathbf{x} = (1, 5, 7)$, $U = \text{span}\{(1, -2, 3), (-1, 1, 1)\}$
 b. $\mathbf{x} = (2, 1, 6)$, $U = \text{span}\{(3, -1, 2), (2, 0, -3)\}$
 c. $\mathbf{x} = (3, 1, 5, 9)$,
 $U = \text{span}\{(1, 0, 1, 1), (0, 1, -1, 1), (-2, 0, 1, 1)\}$
 d. $\mathbf{x} = (2, 0, 1, 6)$,
 $U = \text{span}\{(1, 1, 1, 1), (1, 1, -1, -1), (1, -1, 1, -1)\}$
 e. $\mathbf{x} = (a, b, c, d)$,
 $U = \text{span}\{(1, 0, 0, 0), (0, 1, 0, 0), (0, 0, 1, 0)\}$
 f. $\mathbf{x} = (a, b, c, d)$,
 $U = \text{span}\{(1, -1, 2, 0), (-1, 1, 1, 1)\}$

b. $\mathbf{x} = \frac{1}{182}(271, -221, 1030) + \frac{1}{182}(93, 403, 62)$

d. $\mathbf{x} = \frac{1}{4}(1, 7, 11, 17) + \frac{1}{4}(7, -7, -7, 7)$

f. $\mathbf{x} = \frac{1}{12}(5a - 5b + c - 3d, -5a + 5b - c + 3d, a - b + 11c + 3d, -3a + 3b + 3c + 3d) + \frac{1}{12}(7a + 5b - c + 3d, 5a + 7b + c - 3d, -a + b + c - 3d, 3a - 3b - 3c + 9d)$

Exercise 8.1.3 Let $\mathbf{x} = (1, -2, 1, 6)$ in \mathbb{R}^4 , and let $U = \text{span}\{(2, 1, 3, -4), (1, 2, 0, 1)\}$.

- a. Compute $\text{proj}_U \mathbf{x}$.
 b. Show that $\{(1, 0, 2, -3), (4, 7, 1, 2)\}$ is another orthogonal basis of U .
 c. Use the basis in part (b) to compute $\text{proj}_U \mathbf{x}$.

a. $\frac{1}{10}(-9, 3, -21, 33) = \frac{3}{10}(-3, 1, -7, 11)$

c. $\frac{1}{70}(-63, 21, -147, 231) = \frac{3}{10}(-3, 1, -7, 11)$

Exercise 8.1.4 In each case, use the Gram-Schmidt algorithm to find an orthogonal basis of the subspace U , and find the vector in U closest to \mathbf{x} .

a. $U = \text{span}\{(1, 1, 1), (0, 1, 1)\}$, $\mathbf{x} = (-1, 2, 1)$

b. $U = \text{span}\{(1, -1, 0), (-1, 0, 1)\}$, $\mathbf{x} = (2, 1, 0)$

c. $U = \text{span}\{(1, 0, 1, 0), (1, 1, 1, 0), (1, 1, 0, 0)\}$,
 $\mathbf{x} = (2, 0, -1, 3)$

- d. $U = \text{span}\{(1, -1, 0, 1), (1, 1, 0, 0), (1, 1, 0, 1)\}$,
 $\mathbf{x} = (2, 0, 3, 1)$

- b. $\{(1, -1, 0), \frac{1}{2}(-1, -1, 2)\}$; $\text{proj}_U \mathbf{x} = (1, 0, -1)$

- d. $\{(1, -1, 0, 1), (1, 1, 0, 0), \frac{1}{3}(-1, 1, 0, 2)\}$;
 $\text{proj}_U \mathbf{x} = (2, 0, 0, 1)$

Exercise 8.1.5 Let $U = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$, \mathbf{v}_i in \mathbb{R}^n , and let A be the $k \times n$ matrix with the \mathbf{v}_i as rows.

- a. Show that $U^\perp = \{\mathbf{x} \mid \mathbf{x} \text{ in } \mathbb{R}^n, A\mathbf{x}^T = \mathbf{0}\}$.
 b. Use part (a) to find U^\perp if
 $U = \text{span}\{(1, -1, 2, 1), (1, 0, -1, 1)\}$.

- b. $U^\perp = \text{span}\{(1, 3, 1, 0), (-1, 0, 0, 1)\}$

Exercise 8.1.6

- a. Prove part 1 of Lemma 8.1.2.
 b. Prove part 2 of Lemma 8.1.2.

Exercise 8.1.7 Let U be a subspace of \mathbb{R}^n . If \mathbf{x} in \mathbb{R}^n can be written in any way at all as $\mathbf{x} = \mathbf{p} + \mathbf{q}$ with \mathbf{p} in U and \mathbf{q} in U^\perp , show that necessarily $\mathbf{p} = \text{proj}_U \mathbf{x}$.

Exercise 8.1.8 Let U be a subspace of \mathbb{R}^n and let \mathbf{x} be a vector in \mathbb{R}^n . Using Exercise 8.1.7, or otherwise, show that \mathbf{x} is in U if and only if $\mathbf{x} = \text{proj}_U \mathbf{x}$.

Write $\mathbf{p} = \text{proj}_U \mathbf{x}$. Then \mathbf{p} is in U by definition. If \mathbf{x} is in U , then $\mathbf{x} - \mathbf{p}$ is in U . But $\mathbf{x} - \mathbf{p}$ is also in U^\perp by Theorem 8.1.3, so $\mathbf{x} - \mathbf{p}$ is in $U \cap U^\perp = \{\mathbf{0}\}$. Thus $\mathbf{x} = \mathbf{p}$.

Exercise 8.1.9 Let U be a subspace of \mathbb{R}^n .

- a. Show that $U^\perp = \mathbb{R}^n$ if and only if $U = \{\mathbf{0}\}$.
 b. Show that $U^\perp = \{\mathbf{0}\}$ if and only if $U = \mathbb{R}^n$.

Exercise 8.1.10 If U is a subspace of \mathbb{R}^n , show that $\text{proj}_U \mathbf{x} = \mathbf{x}$ for all \mathbf{x} in U .

Let $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_m\}$ be an orthonormal basis of U . If \mathbf{x} is in U the expansion theorem gives $\mathbf{x} = (\mathbf{x} \cdot \mathbf{f}_1)\mathbf{f}_1 + (\mathbf{x} \cdot \mathbf{f}_2)\mathbf{f}_2 + \dots + (\mathbf{x} \cdot \mathbf{f}_m)\mathbf{f}_m = \text{proj}_U \mathbf{x}$.

Exercise 8.1.11 If U is a subspace of \mathbb{R}^n , show that $\mathbf{x} = \text{proj}_U \mathbf{x} + \text{proj}_{U^\perp} \mathbf{x}$ for all \mathbf{x} in \mathbb{R}^n .

Exercise 8.1.12 If $\{\mathbf{f}_1, \dots, \mathbf{f}_n\}$ is an orthogonal basis of \mathbb{R}^n and $U = \text{span}\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$, show that $U^\perp = \text{span}\{\mathbf{f}_{m+1}, \dots, \mathbf{f}_n\}$.

Exercise 8.1.13 If U is a subspace of \mathbb{R}^n , show that $U^{\perp\perp} = U$. [Hint: Show that $U \subseteq U^{\perp\perp}$, then use Theorem 8.1.4 (3) twice.]

Exercise 8.1.14 If U is a subspace of \mathbb{R}^n , show how to find an $n \times n$ matrix A such that $U = \{\mathbf{x} \mid A\mathbf{x} = \mathbf{0}\}$. [Hint: Exercise 8.1.13.]

Let $\{\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_m\}$ be a basis of U^\perp , and let A be the $n \times n$ matrix with rows $\mathbf{y}_1^T, \mathbf{y}_2^T, \dots, \mathbf{y}_m^T, \mathbf{0}, \dots, \mathbf{0}$. Then $A\mathbf{x} = \mathbf{0}$ if and only if $\mathbf{y}_i \cdot \mathbf{x} = 0$ for each $i = 1, 2, \dots, m$; if and only if \mathbf{x} is in $U^{\perp\perp} = U$.

Exercise 8.1.15 Write \mathbb{R}^n as rows. If A is an $n \times n$ matrix, write its null space as $\text{null } A = \{\mathbf{x} \text{ in } \mathbb{R}^n \mid A\mathbf{x}^T = \mathbf{0}\}$. Show that:

- a) $\text{null } A = (\text{row } A)^\perp$; b) $\text{null } A^T = (\text{col } A)^\perp$.

Exercise 8.1.16 If U and W are subspaces, show that $(U + W)^\perp = U^\perp \cap W^\perp$. [See Exercise 5.1.22.]

Exercise 8.1.17 Think of \mathbb{R}^n as consisting of rows.

- a. Let E be an $n \times n$ matrix, and let $U = \{\mathbf{x}E \mid \mathbf{x} \text{ in } \mathbb{R}^n\}$. Show that the following are equivalent.
- i. $E^2 = E = E^T$ (E is a **projection matrix**).
 - ii. $(\mathbf{x} - \mathbf{x}E) \cdot (\mathbf{y}E) = 0$ for all \mathbf{x} and \mathbf{y} in \mathbb{R}^n .
 - iii. $\text{proj}_U \mathbf{x} = \mathbf{x}E$ for all \mathbf{x} in \mathbb{R}^n . [Hint: For (ii) implies (iii): Write $\mathbf{x} = \mathbf{x}E + (\mathbf{x} - \mathbf{x}E)$ and use the uniqueness argument preceding the definition of $\text{proj}_U \mathbf{x}$. For (iii) implies (ii): $\mathbf{x} - \mathbf{x}E$ is in U^\perp for all \mathbf{x} in \mathbb{R}^n .]
- b. If E is a projection matrix, show that $I - E$ is also a projection matrix.

c. If $EF = 0 = FE$ and E and F are projection matrices, show that $E + F$ is also a projection matrix.

d. If A is $m \times n$ and AA^T is invertible, show that $E = A^T(AA^T)^{-1}A$ is a projection matrix.

$(n - 1) \times (n - 1)$ matrix obtained from A by deleting column i . Define the vector \mathbf{y} in \mathbb{R}^n by

$$\mathbf{y} = [\det A_1 - \det A_2 \ \det A_3 \ \cdots \ (-1)^{n+1} \det A_n]$$

Show that:

a. $\mathbf{x}_i \cdot \mathbf{y} = 0$ for all $i = 1, 2, \dots, n - 1$. [*Hint:*

Write $B_i = \begin{bmatrix} x_i \\ A \end{bmatrix}$ and show that $\det B_i = 0$.]

b. $\mathbf{y} \neq \mathbf{0}$ if and only if $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_{n-1}\}$ is linearly independent. [*Hint:* If some $\det A_i \neq 0$, the rows of A_i are linearly independent. Conversely, if the \mathbf{x}_i are independent, consider $A = UR$ where R is in reduced row-echelon form.]

c. If $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_{n-1}\}$ is linearly independent, use Theorem 8.1.3(3) to show that all solutions to the system of $n - 1$ homogeneous equations

$$A\mathbf{x}^T = \mathbf{0}$$

are given by $t\mathbf{y}$, t a parameter.

d. $E^T = A^T[(AA^T)^{-1}]^T(A^T)^T = A^T[(AA^T)^T]^{-1}A = A^T[AA^T]^{-1}A = E$
 $E^2 = A^T(AA^T)^{-1}AA^T(AA^T)^{-1}A = A^T(AA^T)^{-1}A = E$

Exercise 8.1.18 Let A be an $n \times n$ matrix of rank r . Show that there is an invertible $n \times n$ matrix U such that UA is a row-echelon matrix with the property that the first r rows are orthogonal. [*Hint:* Let R be the row-echelon form of A , and use the Gram-Schmidt process on the nonzero rows of R from the bottom up. Use Lemma 2.4.1.]

Exercise 8.1.19 Let A be an $(n - 1) \times n$ matrix with rows $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_{n-1}$ and let A_i denote the

