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LINEAR ALGEBRA with Applications

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Adapted for

Emory University

Math 221

Linear Algebra

Sections 1 & 2

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Course page

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8.5 Computing Eigenvalues

In practice, the problem of finding eigenvalues of a matrix is virtually never solved by finding the roots of the characteristic polynomial. This is difficult for large matrices and iterative methods are much better. Two such methods are described briefly in this section.

The Power Method

In Chapter 3 our initial rationale for diagonalizing matrices was to be able to compute the powers of a square matrix, and the eigenvalues were needed to do this. In this section, we are interested in efficiently computing eigenvalues, and it may come as no surprise that the first method we discuss uses the powers of a matrix.

Recall that an eigenvalue λ of an $n \times n$ matrix A is called a **dominant eigenvalue** if λ has multiplicity 1, and

$$|\lambda| > |\mu| \quad \text{for all eigenvalues } \mu \neq \lambda$$

Any corresponding eigenvector is called a **dominant eigenvector** of A . When such an eigenvalue exists, one technique for finding it is as follows: Let \mathbf{x}_0 in \mathbb{R}^n be a first approximation to a dominant eigenvector λ , and compute successive approximations $\mathbf{x}_1, \mathbf{x}_2, \dots$ as follows:

$$\mathbf{x}_1 = A\mathbf{x}_0 \quad \mathbf{x}_2 = A\mathbf{x}_1 \quad \mathbf{x}_3 = A\mathbf{x}_2 \quad \dots$$

In general, we define

$$\mathbf{x}_{k+1} = A\mathbf{x}_k \quad \text{for each } k \geq 0$$

If the first estimate \mathbf{x}_0 is good enough, these vectors \mathbf{x}_n will approximate the dominant eigenvector λ (see below). This technique is called the **power method** (because $\mathbf{x}_k = A^k\mathbf{x}_0$ for each $k \geq 1$). Observe that if \mathbf{z} is any eigenvector corresponding to λ , then

$$\frac{\mathbf{z} \cdot (A\mathbf{z})}{\|\mathbf{z}\|^2} = \frac{\mathbf{z} \cdot (\lambda\mathbf{z})}{\|\mathbf{z}\|^2} = \lambda$$

Because the vectors $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n, \dots$ approximate dominant eigenvectors, this suggests that we define the **Rayleigh quotients** as follows:

$$r_k = \frac{\mathbf{x}_k \cdot \mathbf{x}_{k+1}}{\|\mathbf{x}_k\|^2} \quad \text{for } k \geq 1$$

Then the numbers r_k approximate the dominant eigenvalue λ .

Example 8.5.1

Use the power method to approximate a dominant eigenvector and eigenvalue of

$$A = \begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix}.$$

Solution. The eigenvalues of A are 2 and -1 , with eigenvectors $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ -2 \end{bmatrix}$. Take

$\mathbf{x}_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ as the first approximation and compute $\mathbf{x}_1, \mathbf{x}_2, \dots$, successively, from $\mathbf{x}_1 = A\mathbf{x}_0, \mathbf{x}_2 = A\mathbf{x}_1, \dots$. The result is

$$\mathbf{x}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad \mathbf{x}_2 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \quad \mathbf{x}_3 = \begin{bmatrix} 5 \\ 6 \end{bmatrix}, \quad \mathbf{x}_4 = \begin{bmatrix} 11 \\ 10 \end{bmatrix}, \quad \mathbf{x}_5 = \begin{bmatrix} 21 \\ 22 \end{bmatrix}, \quad \dots$$

These vectors are approaching scalar multiples of the dominant eigenvector $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

Moreover, the Rayleigh quotients are

$$r_1 = \frac{7}{5}, \quad r_2 = \frac{27}{13}, \quad r_3 = \frac{115}{61}, \quad r_4 = \frac{451}{221}, \quad \dots$$

and these are approaching the dominant eigenvalue 2.

To see why the power method works, let $\lambda_1, \lambda_2, \dots, \lambda_m$ be eigenvalues of A with λ_1 dominant and let $\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_m$ be corresponding eigenvectors. What is required is that the first approximation \mathbf{x}_0 be a linear combination of these eigenvectors:

$$\mathbf{x}_0 = a_1\mathbf{y}_1 + a_2\mathbf{y}_2 + \dots + a_m\mathbf{y}_m \quad \text{with } a_1 \neq 0$$

If $k \geq 1$, the fact that $\mathbf{x}_k = A^k\mathbf{x}_0$ and $A^k\mathbf{y}_i = \lambda_i^k\mathbf{y}_i$ for each i gives

$$\mathbf{x}_k = a_1\lambda_1^k\mathbf{y}_1 + a_2\lambda_2^k\mathbf{y}_2 + \dots + a_m\lambda_m^k\mathbf{y}_m \quad \text{for } k \geq 1$$

Hence

$$\frac{1}{\lambda_1^k}\mathbf{x}_k = a_1\mathbf{y}_1 + a_2\left(\frac{\lambda_2}{\lambda_1}\right)^k\mathbf{y}_2 + \dots + a_m\left(\frac{\lambda_m}{\lambda_1}\right)^k\mathbf{y}_m$$

The right side approaches $a_1\mathbf{y}_1$ as k increases because λ_1 is dominant ($|\frac{\lambda_i}{\lambda_1}| < 1$ for each $i > 1$). Because $a_1 \neq 0$, this means that \mathbf{x}_k approximates the dominant eigenvector $a_1\lambda_1^k\mathbf{y}_1$.

The power method requires that the first approximation \mathbf{x}_0 be a linear combination of eigenvectors. (In Example 8.5.1 the eigenvectors form a basis of \mathbb{R}^2 .) But even in this case the method fails if $a_1 = 0$, where a_1 is the coefficient of the dominant eigenvector (try $\mathbf{x}_0 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$ in Example 8.5.1).

In general, the rate of convergence is quite slow if any of the ratios $|\frac{\lambda_i}{\lambda_1}|$ is near 1. Also, because the method requires repeated multiplications by A , it is not recommended unless these multiplications are easy to carry out (for example, if most of the entries of A are zero).

QR-Algorithm

A much better method for approximating the eigenvalues of an invertible matrix A depends on the factorization (using the Gram-Schmidt algorithm) of A in the form

$$A = QR$$

where Q is orthogonal and R is invertible and upper triangular (see Theorem 8.4.2). The **QR-algorithm** uses this repeatedly to create a sequence of matrices $A_1 = A$, A_2 , A_3 , ..., as follows:

1. Define $A_1 = A$ and factor it as $A_1 = Q_1 R_1$.
2. Define $A_2 = R_1 Q_1$ and factor it as $A_2 = Q_2 R_2$.
3. Define $A_3 = R_2 Q_2$ and factor it as $A_3 = Q_3 R_3$.
- ⋮

In general, A_k is factored as $A_k = Q_k R_k$ and we define $A_{k+1} = R_k Q_k$. Then A_{k+1} is similar to A_k [in fact, $A_{k+1} = R_k Q_k = (Q_k^{-1} A_k) Q_k$], and hence each A_k has the same eigenvalues as A . If the eigenvalues of A are real and have distinct absolute values, the remarkable thing is that the sequence of matrices A_1, A_2, A_3, \dots converges to an upper triangular matrix with these eigenvalues on the main diagonal. [See below for the case of complex eigenvalues.]

Example 8.5.2

If $A = \begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix}$ as in Example 8.5.1, use the QR-algorithm to approximate the eigenvalues.

Solution. The matrices A_1 , A_2 , and A_3 are as follows:

$$A_1 = \begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix} = Q_1 R_1 \quad \text{where } Q_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix} \text{ and } R_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 5 & 1 \\ 0 & 2 \end{bmatrix}$$

$$A_2 = \frac{1}{5} \begin{bmatrix} 7 & 9 \\ 4 & -2 \end{bmatrix} = \begin{bmatrix} 1.4 & -1.8 \\ -0.8 & -0.4 \end{bmatrix} = Q_2 R_2$$

$$\text{where } Q_2 = \frac{1}{\sqrt{65}} \begin{bmatrix} 7 & 4 \\ 4 & -7 \end{bmatrix} \text{ and } R_2 = \frac{1}{\sqrt{65}} \begin{bmatrix} 13 & 11 \\ 0 & 10 \end{bmatrix}$$

$$A_3 = \frac{1}{13} \begin{bmatrix} 27 & -5 \\ 8 & -14 \end{bmatrix} = \begin{bmatrix} 2.08 & -0.38 \\ 0.62 & -1.08 \end{bmatrix}$$

This is converging to $\begin{bmatrix} 2 & * \\ 0 & -1 \end{bmatrix}$ and so is approximating the eigenvalues 2 and -1 on the main diagonal.

It is beyond the scope of this book to pursue a detailed discussion of these methods. The reader is referred to J. M. Wilkinson, *The Algebraic Eigenvalue Problem* (Oxford, England: Oxford University

Press, 1965) or G. W. Stewart, *Introduction to Matrix Computations* (New York: Academic Press, 1973). We conclude with some remarks on the QR-algorithm.

Shifting. Convergence is accelerated if, at stage k of the algorithm, a number s_k is chosen and $A_k - s_k I$ is factored in the form $Q_k R_k$ rather than A_k itself. Then

$$Q_k^{-1} A_k Q_k = Q_k^{-1} (Q_k R_k + s_k I) Q_k = R_k Q_k + s_k I$$

so we take $A_{k+1} = R_k Q_k + s_k I$. If the shifts s_k are carefully chosen, convergence can be greatly improved.

Preliminary Preparation. A matrix such as

$$\begin{bmatrix} * & * & * & * & * \\ * & * & * & * & * \\ 0 & * & * & * & * \\ 0 & 0 & * & * & * \\ 0 & 0 & 0 & * & * \end{bmatrix}$$

is said to be in **upper Hessenberg** form, and the QR-factorizations of such matrices are greatly simplified. Given an $n \times n$ matrix A , a series of orthogonal matrices H_1, H_2, \dots, H_m (called **Householder matrices**) can be easily constructed such that

$$B = H_m^T \cdots H_1^T A H_1 \cdots H_m$$

is in upper Hessenberg form. Then the QR-algorithm can be efficiently applied to B and, because B is similar to A , it produces the eigenvalues of A .

Complex Eigenvalues. If some of the eigenvalues of a real matrix A are not real, the QR-algorithm converges to a block upper triangular matrix where the diagonal blocks are either 1×1 (the real eigenvalues) or 2×2 (each providing a pair of conjugate complex eigenvalues of A).

Exercises for 8.5

Exercise 8.5.1 In each case, find the exact eigenvalues and determine corresponding eigenvectors.

Then start with $\mathbf{x}_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and compute \mathbf{x}_4 and r_3 using the power method.

a) $A = \begin{bmatrix} 2 & -4 \\ -3 & 3 \end{bmatrix}$

b) $A = \begin{bmatrix} 5 & 2 \\ -3 & -2 \end{bmatrix}$

c) $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$

d) $A = \begin{bmatrix} 3 & 1 \\ 1 & 0 \end{bmatrix}$

b. Eigenvalues 4, -1; eigenvectors $\begin{bmatrix} 2 \\ -1 \end{bmatrix}$,

$\begin{bmatrix} 1 \\ -3 \end{bmatrix}$; $\mathbf{x}_4 = \begin{bmatrix} 409 \\ -203 \end{bmatrix}$; $r_3 = 3.94$

d. Eigenvalues $\lambda_1 = \frac{1}{2}(3 + \sqrt{13})$, $\lambda_2 = \frac{1}{2}(3 - \sqrt{13})$; eigenvectors $\begin{bmatrix} \lambda_1 \\ 1 \end{bmatrix}$, $\begin{bmatrix} \lambda_2 \\ 1 \end{bmatrix}$; $\mathbf{x}_4 = \begin{bmatrix} 142 \\ 43 \end{bmatrix}$; $r_3 = 3.3027750$ (The true value is $\lambda_1 = 3.3027756$, to seven decimal places.)

Exercise 8.5.2 In each case, find the exact eigenvalues and then approximate them using the QR-

algorithm.

$$\text{a) } A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \quad \text{b) } A = \begin{bmatrix} 3 & 1 \\ 1 & 0 \end{bmatrix}$$

b. Eigenvalues $\lambda_1 = \frac{1}{2}(3 + \sqrt{13}) = 3.302776$, $\lambda_2 = \frac{1}{2}(3 - \sqrt{13}) = -0.302776$ $A_1 = \begin{bmatrix} 3 & 1 \\ 1 & 0 \end{bmatrix}$, $Q_1 = \frac{1}{\sqrt{10}} \begin{bmatrix} 3 & -1 \\ 1 & 3 \end{bmatrix}$, $R_1 = \frac{1}{\sqrt{10}} \begin{bmatrix} 10 & 3 \\ 0 & -1 \end{bmatrix}$

$$A_2 = \frac{1}{10} \begin{bmatrix} 33 & -1 \\ -1 & -3 \end{bmatrix},$$

$$Q_2 = \frac{1}{\sqrt{1090}} \begin{bmatrix} 33 & 1 \\ -1 & 33 \end{bmatrix},$$

$$R_2 = \frac{1}{\sqrt{1090}} \begin{bmatrix} 109 & -3 \\ 0 & -10 \end{bmatrix}$$

$$A_3 = \frac{1}{109} \begin{bmatrix} 360 & 1 \\ 1 & -33 \end{bmatrix}$$

$$= \begin{bmatrix} 3.302775 & 0.009174 \\ 0.009174 & -0.302775 \end{bmatrix}$$

Exercise 8.5.3 Apply the power method to $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$, starting at $\mathbf{x}_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. Does it converge? Explain.

Exercise 8.5.4 If A is symmetric, show that each matrix A_k in the QR-algorithm is also symmetric. Deduce that they converge to a diagonal matrix.

Use induction on k . If $k = 1$, $A_1 = A$. In general $A_{k+1} = Q_k^{-1}A_kQ_k = Q_k^T A_k Q_k$, so the fact that $A_k^T = A_k$ implies $A_{k+1}^T = A_{k+1}$. The eigenvalues of A are all real (Theorem 5.5.5), so the A_k converge to an upper triangular matrix T . But T must also be symmetric (it is the limit of symmetric matrices), so it is diagonal.

Exercise 8.5.5 Apply the QR-algorithm to

$$A = \begin{bmatrix} 2 & -3 \\ 1 & -2 \end{bmatrix}. \text{ Explain.}$$

Exercise 8.5.6 Given a matrix A , let A_k , Q_k , and R_k , $k \geq 1$, be the matrices constructed in the QR-algorithm. Show that $A_k = (Q_1 Q_2 \cdots Q_k)(R_k \cdots R_2 R_1)$ for each $k \geq 1$ and hence that this is a QR-factorization of A_k .

[*Hint:* Show that $Q_k R_k = R_{k-1} Q_{k-1}$ for each $k \geq 2$, and use this equality to compute $(Q_1 Q_2 \cdots Q_k)(R_k \cdots R_2 R_1)$ “from the centre out.” Use the fact that $(AB)^{n+1} = A(BA)^n B$ for any square matrices A and B .]

