

Math 221: LINEAR ALGEBRA

Chapter 5. Vector Space \mathbb{R}^n

§5-3. Orthogonality

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¹Slides are adapted from those by Karen Seyffarth from University of Calgary.

The Dot Product

The Cauchy Inequality

Orthogonality

Orthogonality and Independence

Fourier Expansion

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Definitions

Let $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$ and $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$ be vectors in \mathbb{R}^n .

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1. The **dot product** of \vec{x} and \vec{y} is

$$\vec{x} \cdot \vec{y} = x_1y_1 + x_2y_2 + \cdots + x_ny_n = \vec{x}^T \vec{y}.$$

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3. \vec{x} is called a **unit vector** if $\|\vec{x}\| = 1$.

Theorem (Properties of length and the dot product)

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6. $\|a\vec{x}\| = |a| \|\vec{x}\|$.

Example

Let $\vec{x}, \vec{y} \in \mathbb{R}^n$. Then

$$\begin{aligned} \|\vec{x} + \vec{y}\|^2 &= (\vec{x} + \vec{y}) \cdot (\vec{x} + \vec{y}) \\ &= \vec{x} \cdot \vec{x} + \vec{x} \cdot \vec{y} + \vec{y} \cdot \vec{x} + \vec{y} \cdot \vec{y} \\ &= \vec{x} \cdot \vec{x} + 2(\vec{x} \cdot \vec{y}) + \vec{y} \cdot \vec{y} \\ &= \|\vec{x}\|^2 + 2(\vec{x} \cdot \vec{y}) + \|\vec{y}\|^2. \end{aligned}$$

Problem

Let $\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_k\} \in \mathbb{R}^n$ and suppose $\mathbb{R}^n = \text{span}\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_k\}$. Furthermore, suppose that there exists a vector $\vec{x} \in \mathbb{R}^n$ for which $\vec{x} \cdot \vec{f}_j = 0$ for all j , $1 \leq j \leq k$. Show that $\vec{x} = \vec{0}_n$.

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Proof.

Write $\vec{x} = t_1\vec{f}_1 + t_2\vec{f}_2 + \dots + t_k\vec{f}_k$ for some $t_1, t_2, \dots, t_k \in \mathbb{R}$ (this is possible because $\vec{f}_1, \vec{f}_2, \dots, \vec{f}_k$ span \mathbb{R}^n , is this representation unique?).

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Since $\|\vec{x}\|^2 = 0$, $\|\vec{x}\| = 0$. By the previous theorem, $\|\vec{x}\| = 0$ if and only if $\vec{x} = \vec{0}_n$. Therefore, $\vec{x} = \vec{0}_n$. ■

The Dot Product

The Cauchy Inequality

Orthogonality

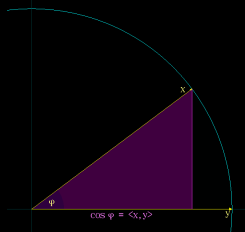
Orthogonality and Independence

Fourier Expansion

Cauchy-Schwartz Inequality

Theorem (Cauchy-Schwartz Inequality)

If $\vec{x}, \vec{y} \in \mathbb{R}^n$, then $|\vec{x} \cdot \vec{y}| \leq \|\vec{x}\| \|\vec{y}\|$ with equality if and only if $\{\vec{x}, \vec{y}\}$ is linearly dependent.



$$\left| \frac{\vec{x}}{\|\vec{x}\|} \cdot \frac{\vec{y}}{\|\vec{y}\|} \right| \leq 1$$

$\{\vec{x}, \vec{y}\}$ is linearly dependent $\Leftrightarrow \vec{x} = t\vec{y}$, for some $t \in \mathbb{R}$.

Proof.

Let $\vec{x}, \vec{y} \in \mathbb{R}^n$ and $t \in \mathbb{R}$. Then

$$\begin{aligned} 0 \leq \|t\vec{x} + \vec{y}\|^2 &= (t\vec{x} + \vec{y}) \cdot (t\vec{x} + \vec{y}) \\ &= t^2\vec{x} \cdot \vec{x} + 2t\vec{x} \cdot \vec{y} + \vec{y} \cdot \vec{y} \\ &= t^2\|\vec{x}\|^2 + 2t(\vec{x} \cdot \vec{y}) + \|\vec{y}\|^2. \end{aligned}$$

The quadratic $t^2\|\vec{x}\|^2 + 2t(\vec{x} \cdot \vec{y}) + \|\vec{y}\|^2$ in t is always nonnegative, so it does not have distinct real roots. Thus, if we use the quadratic formula to solve for t , the discriminant must be non-positive, i.e.,

$$\Delta = (2\vec{x} \cdot \vec{y})^2 - 4\|\vec{x}\|^2\|\vec{y}\|^2 \leq 0$$

Therefore, $(2\vec{x} \cdot \vec{y})^2 \leq 4\|\vec{x}\|^2\|\vec{y}\|^2$. Since both sides of the inequality are nonnegative, we can take (positive) square roots of both sides:

$$|2\vec{x} \cdot \vec{y}| \leq 2\|\vec{x}\| \|\vec{y}\|$$

Therefore, $|\vec{x} \cdot \vec{y}| \leq \|\vec{x}\| \|\vec{y}\|$. What remains is to show that $|\vec{x} \cdot \vec{y}| = \|\vec{x}\| \|\vec{y}\|$ if and only if $\{\vec{x}, \vec{y}\}$ is linearly dependent. ■

Proof. (continued)

First suppose that $\{\vec{x}, \vec{y}\}$ is dependent. Then by symmetry (of \vec{x} and \vec{y}), $\vec{x} = k\vec{y}$ for some $k \in \mathbb{R}$. Hence

$$|\vec{x} \cdot \vec{y}| = |(k\vec{y}) \cdot \vec{y}| = |k| |\vec{y} \cdot \vec{y}| = |k| \|\vec{y}\|^2, \quad \text{and} \quad \|\vec{x}\| \|\vec{y}\| = \|k\vec{y}\| \|\vec{y}\| = |k| \|\vec{y}\|^2,$$

$$\text{so } |\vec{x} \cdot \vec{y}| = \|\vec{x}\| \|\vec{y}\|.$$

Conversely, suppose $\{\vec{x}, \vec{y}\}$ is independent; then $t\vec{x} + \vec{y} \neq \vec{0}_n$ for all $t \in \mathbb{R}$, so $\|t\vec{x} + \vec{y}\|^2 > 0$ for all $t \in \mathbb{R}$. Thus the quadratic

$$t^2 \|\vec{x}\|^2 + 2t(\vec{x} \cdot \vec{y}) + \|\vec{y}\|^2 > 0$$

so has no real roots. It follows that the the discriminant is negative, i.e.,

$$(2\vec{x} \cdot \vec{y})^2 - 4\|\vec{x}\|^2 \|\vec{y}\|^2 < 0.$$

Therefore, $(2\vec{x} \cdot \vec{y})^2 < 4\|\vec{x}\|^2 \|\vec{y}\|^2$; taking square roots of both sides (they are both nonnegative) and dividing by two gives us

$$|\vec{x} \cdot \vec{y}| < \|\vec{x}\| \|\vec{y}\|,$$

showing that equality is impossible. ■

Corollary (Triangle Inequality I)

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Since both sides of the inequality are nonnegative, we take (positive) square roots of both sides:

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If $\vec{x}, \vec{y} \in \mathbb{R}^n$, then the **distance** between \vec{x} and \vec{y} is defined as

$$d(\vec{x}, \vec{y}) = \|\vec{x} - \vec{y}\|.$$

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- ▶ Let $\vec{x}, \vec{y} \in \mathbb{R}^n$. We say that two vectors \vec{x} and \vec{y} are **orthogonal** if $\vec{x} \cdot \vec{y} = 0$.

Orthogonality

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- ▶ A set $X = \{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\} \subseteq \mathbb{R}^n$ is an **orthonormal** set if X is an orthogonal set of **unit vectors**, i.e., $\|\vec{x}_i\| = 1$ for all i , $1 \leq i \leq k$.

Examples

1. The standard basis $\{\vec{e}_1, \dots, \vec{e}_n\}$ of \mathbb{R}^n is an orthonormal set (and hence an orthogonal set).

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$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} \right\}$$

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$$\left\{ \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} \right\}$$

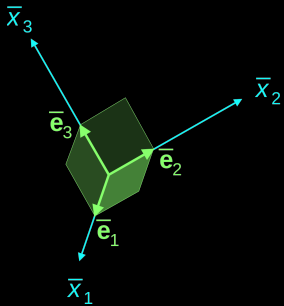
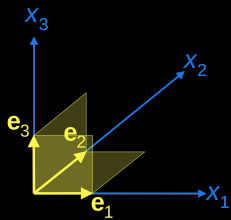
is an orthonormal subset of \mathbb{R}^4 .

Definition

Normalizing an orthogonal set is the process of turning an orthogonal (but not orthonormal) set into an orthonormal set. If $\{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\}$ is an orthogonal subset of \mathbb{R}^n , then

$$\left\{ \frac{1}{\|\vec{x}_1\|} \vec{x}_1, \frac{1}{\|\vec{x}_2\|} \vec{x}_2, \dots, \frac{1}{\|\vec{x}_k\|} \vec{x}_k \right\}$$

is an orthonormal set.



Problem

Verify that

$$\left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix} \right\}$$

is an orthogonal set, and normalize this set.

Solution

$$\begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} = 0 - 2 + 2 = 0,$$

$$\begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix} = 0 + 2 - 2 = 0,$$

$$\begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix} = 5 - 1 - 4 = 0,$$

proving that the set is orthogonal. Normalizing gives us the orthonormal set

$$\left\{ \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \frac{1}{\sqrt{5}} \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{30}} \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix} \right\}.$$



Theorem (Pythagoras' Theorem)

If $\{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\} \subseteq \mathbb{R}^n$ is orthogonal, then

$$\|\vec{x}_1 + \vec{x}_2 + \dots + \vec{x}_k\|^2 = \|\vec{x}_1\|^2 + \|\vec{x}_2\|^2 + \dots + \|\vec{x}_k\|^2.$$

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Start with

$$\|\vec{x}_1 + \vec{x}_2 + \dots + \vec{x}_k\|^2 = (\vec{x}_1 + \vec{x}_2 + \dots + \vec{x}_k) \cdot (\vec{x}_1 + \vec{x}_2 + \dots + \vec{x}_k)$$

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The second last equality follows from the fact that the set is orthogonal, so for all i and j , $i \neq j$ and $1 \leq i, j \leq k$, $\vec{x}_i \cdot \vec{x}_j = 0$. Thus, the only nonzero terms are the ones of the form $\vec{x}_i \cdot \vec{x}_i$, $1 \leq i \leq k$. ■

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If $S = \{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\} \subseteq \mathbb{R}^n$ is an orthogonal set, then S is independent.

Orthogonality and Independence

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Form the linear equation: $t_1\vec{x}_1 + t_2\vec{x}_2 + \dots + t_k\vec{x}_k = \vec{0}$. We need to check whether there is only trivial solution.

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$$0 = (t_1\vec{x}_1 + t_2\vec{x}_2 + \dots + t_k\vec{x}_k) \cdot \vec{x}_i = t_i\vec{x}_i \cdot \vec{x}_i = t_i\|\vec{x}_i\|^2,$$

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since $t_j\vec{x}_j \cdot \vec{x}_i = 0$ for all j , $1 \leq j \leq k$ where $j \neq i$. Since $\vec{x}_i \neq \vec{0}_n$ and $t_i\|\vec{x}_i\|^2 = 0$, it follows that $t_i = 0$ for all i , $1 \leq i \leq k$. Therefore, S is linearly independent. ■

Example

Given an arbitrary vector

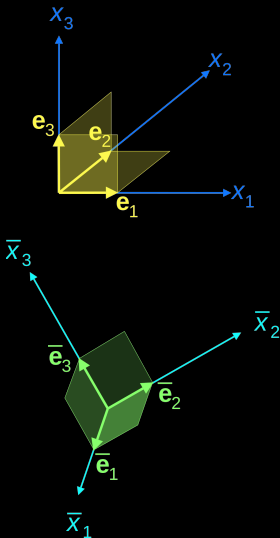
$$\vec{x} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \in \mathbb{R}^n,$$

it is trivial to express \vec{x} as a linear combination of the standard basis vectors of \mathbb{R}^n , $\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$:

$$\vec{x} = a_1\vec{e}_1 + a_2\vec{e}_2 + \dots + a_n\vec{e}_n.$$

Problem

Given any orthogonal basis B of \mathbb{R}^n (so not necessarily the standard basis), and an arbitrary vector $\vec{x} \in \mathbb{R}^n$, how do we express \vec{x} as a linear combination of the vectors in B ?



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Theorem (Fourier Expansion)

Let $\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_m\}$ be an orthogonal basis of a subspace U of \mathbb{R}^n . Then for any $\vec{x} \in U$,

$$\vec{x} = \left(\frac{\vec{x} \cdot \vec{f}_1}{\|\vec{f}_1\|^2} \right) \vec{f}_1 + \left(\frac{\vec{x} \cdot \vec{f}_2}{\|\vec{f}_2\|^2} \right) \vec{f}_2 + \dots + \left(\frac{\vec{x} \cdot \vec{f}_m}{\|\vec{f}_m\|^2} \right) \vec{f}_m.$$

This expression is called the **Fourier expansion** of \vec{x} , and

$$\frac{\vec{x} \cdot \vec{f}_j}{\|\vec{f}_j\|^2}, \quad j = 1, 2, \dots, m$$

are called the **Fourier coefficients**.

Example

Let $\vec{f}_1 = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$, $\vec{f}_2 = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$, and $\vec{f}_3 = \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix}$, and let $\vec{x} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

We have seen that $B = \{\vec{f}_1, \vec{f}_2, \vec{f}_3\}$ is an orthogonal subset of \mathbb{R}^3 .

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To express \vec{x} as a linear combination of the vectors of B , apply the Fourier Expansion Theorem. Assume $\vec{x} = t_1\vec{f}_1 + t_2\vec{f}_2 + t_3\vec{f}_3$.

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Therefore,

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + \frac{3}{5} \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} + \frac{2}{15} \begin{bmatrix} 5 \\ 1 \\ -2 \end{bmatrix}.$$

Proof. (Fourier Expansion)

Let $\vec{x} \in U$. Since $\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_m\}$ is a basis of U , $\vec{x} = t_1\vec{f}_1 + t_2\vec{f}_2 + \dots + t_m\vec{f}_m$ for some $t_1, t_2, \dots, t_m \in \mathbb{R}$.

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$$\vec{x} \cdot \vec{f}_i = (t_1\vec{f}_1 + t_2\vec{f}_2 + \dots + t_m\vec{f}_m) \cdot \vec{f}_i$$

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Remark

If $\{\vec{f}_1, \vec{f}_2, \dots, \vec{f}_m\}$ is an orthonormal basis, then the Fourier coefficients are simply $t_j = \vec{x} \cdot \vec{f}_j$, $j = 1, 2, \dots, m$.

Problem

$$\text{Let } \vec{f}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{f}_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{f}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \quad \vec{f}_4 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix}.$$

Show that $B = \{\vec{f}_1, \vec{f}_2, \vec{f}_3, \vec{f}_4\}$ is an orthogonal basis of \mathbb{R}^4 , and express $\vec{x} = [a \ b \ c \ d]^T$ as a linear combination of $\vec{f}_1, \vec{f}_2, \vec{f}_3$ and \vec{f}_4 .

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Solution

Computing $\vec{f}_i \cdot \vec{f}_j$ for $1 \leq i < j \leq 4$ gives us

$$\begin{aligned} \vec{f}_1 \cdot \vec{f}_2 &= 0, & \vec{f}_1 \cdot \vec{f}_3 &= 0, & \vec{f}_1 \cdot \vec{f}_4 &= 0, \\ \vec{f}_2 \cdot \vec{f}_3 &= 0, & \vec{f}_2 \cdot \vec{f}_4 &= 0, & \vec{f}_3 \cdot \vec{f}_4 &= 0. \end{aligned}$$

Hence, B is an orthogonal set.

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Hence, B is an orthogonal set. It follows that B is independent, and since $|B| = 4 = \dim(\mathbb{R}^4)$, B also spans \mathbb{R}^4 . Therefore, B is an orthogonal basis of \mathbb{R}^4 . By the Fourier Expansion Theorem,

$$\vec{x} = \left(\frac{a+b}{2}\right) \vec{f}_1 + \left(\frac{a-b}{2}\right) \vec{f}_2 + \left(\frac{c+d}{2}\right) \vec{f}_3 + \left(\frac{c-d}{2}\right) \vec{f}_4.$$

