



Optimal Rank-Constrained Mappings for Linear ED Architectures

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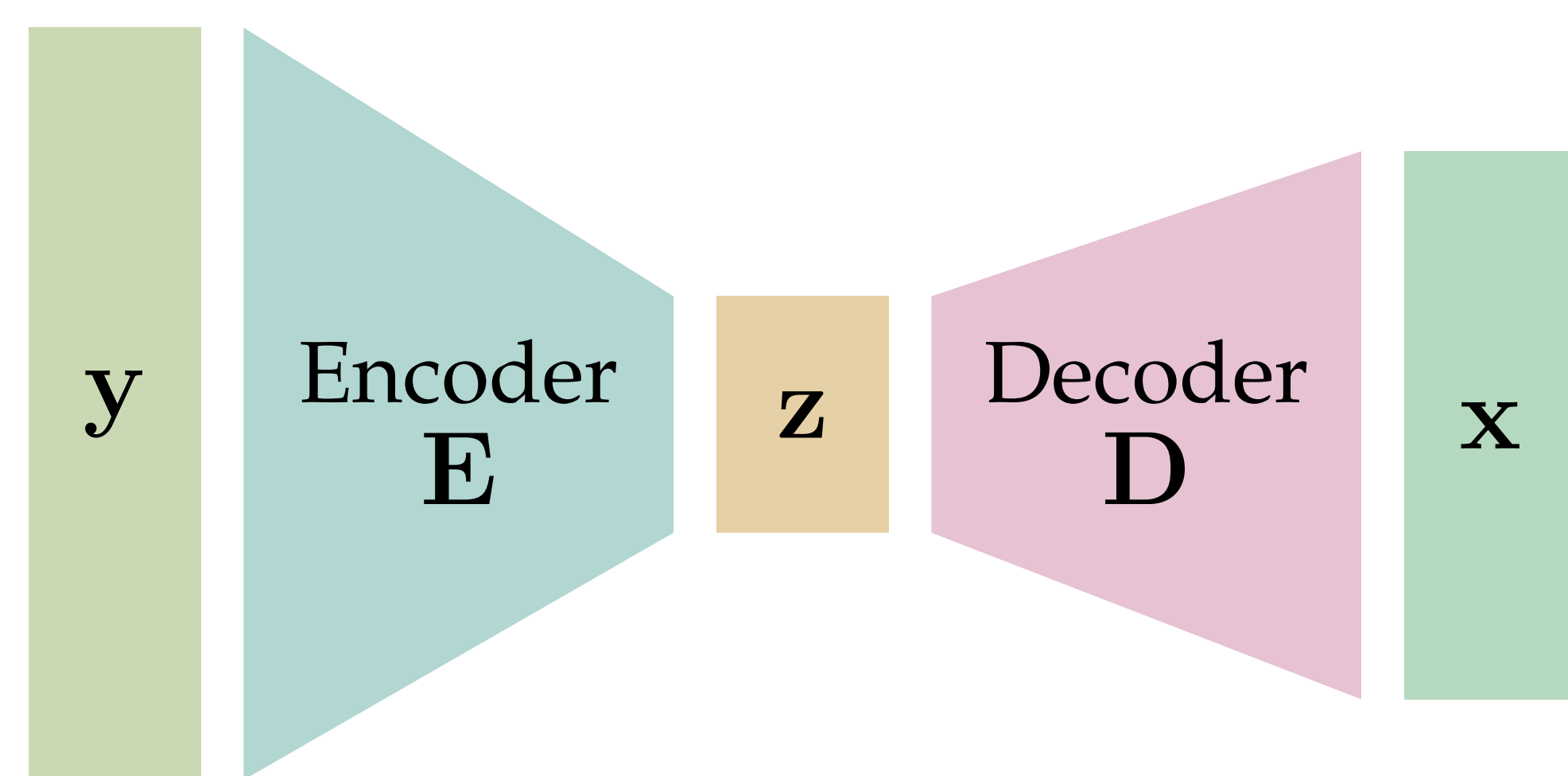
MOTIVATION

Inverse Problem: Given $y = \mathbf{F}x + \varepsilon$, recover the parameters x given observations y and forward operator \mathbf{F} .

- Classical inversion methods struggle with ill-posed and high dimensional problems.
- Data-driven methods are robust to noise, scalable, and adaptable.

Goal: Use encoder-decoder architectures to solve inverse problems via a Bayes risk approach.

ENCODER-DECODER ARCHITECTURE



- Lower dimensional representation of data improves robustness to noise and efficiency
- Bayesian approach incorporates underlying probability distributions and better quantifies uncertainty

THEORETICAL RESULTS

Background

- X is a random variable with second moment $\Gamma_X = \mathbf{L}_X \mathbf{L}_X^\top$, covariance $\mathbf{S}_X = \mathbf{K}_X \mathbf{K}_X^\top$, and mean μ_X
- \mathcal{E} is a random noise variable with second moment $\Gamma_{\mathcal{E}} = \mathbf{L}_{\mathcal{E}} \mathbf{L}_{\mathcal{E}}^\top$
- \mathbf{F} is a known linear forward operator
- Y is a random variable such that $Y = \mathbf{F}X + \mathcal{E}$, with second moment $\Gamma_Y = \mathbf{L}_Y \mathbf{L}_Y^\top$
- Let $(\mathbf{A})_r = \mathbf{U}_{\mathbf{A},r} \Sigma_{\mathbf{A},r} \mathbf{V}_{\mathbf{A},r}^\top$ denote the rank- r truncated SVD of a matrix \mathbf{A} [1]

Minimization Problem

$$\begin{aligned} & \min_{\text{rank}(\mathbf{A}) \leq r} \mathbb{E} \|\mathbf{A}Y - X\|_2^2 \\ & \min_{\text{rank}(\mathbf{A}) \leq r} \mathbb{E} \|\mathbf{A}(X + \mathcal{E}) - X\|_2^2 \\ & \min_{\text{rank}(\mathbf{A}) \leq r} \mathbb{E} \|\mathbf{A}X - Y\|_2^2 \\ & \min_{\text{rank}(\mathbf{A}) \leq r} \mathbb{E} \|\mathbf{A}X + \mathbf{b} - X\|_2^2 \\ & \min_{\text{rank}(\mathbf{A}) \leq r} \mathbb{E} \|\mathbf{A}X - X\|_2^2 \end{aligned}$$

Result

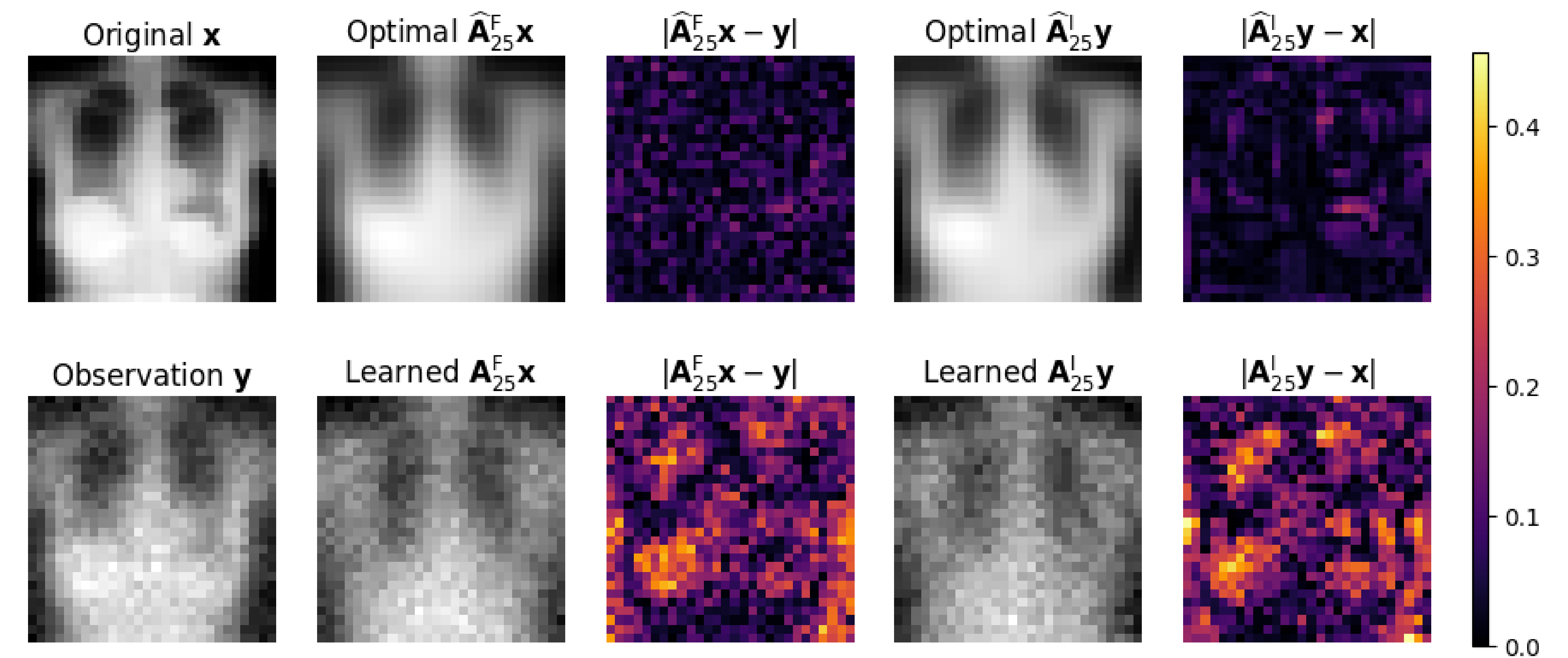
$$\begin{aligned} \hat{\mathbf{A}} &= (\Gamma_X \mathbf{F}^\top \mathbf{L}_Y^{-\top})_r \mathbf{L}_Y^{-1} \\ \hat{\mathbf{A}} &= (\Gamma_X \mathbf{L}_Y^{-\top})_r \mathbf{L}_Y^{-1} \\ \hat{\mathbf{A}} &= (\mathbf{F} \mathbf{L}_X)_r \mathbf{L}_X^\dagger \\ \hat{\mathbf{A}} &= \mathbf{U}_{\mathbf{K}_X,r} \mathbf{U}_{\mathbf{K}_X,r}^\top \quad \text{and} \quad \hat{\mathbf{b}} = (\mathbf{I} - \mathbf{A})\mu_X \\ \hat{\mathbf{A}} &= \mathbf{U}_{\mathbf{L}_X,r} \mathbf{U}_{\mathbf{L}_X,r}^\top \end{aligned}$$

ACKNOWLEDGMENTS

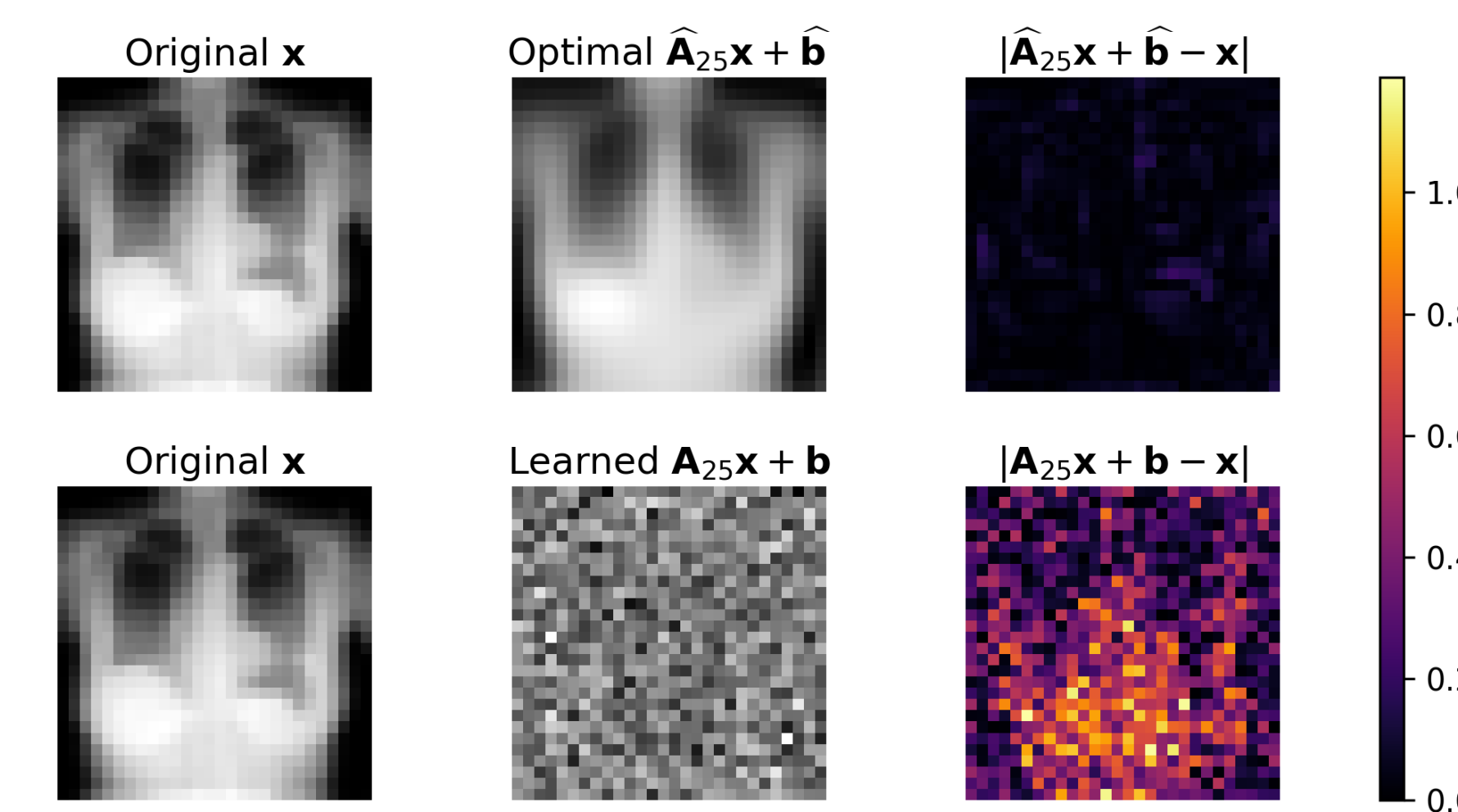
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NUMERICAL RESULTS

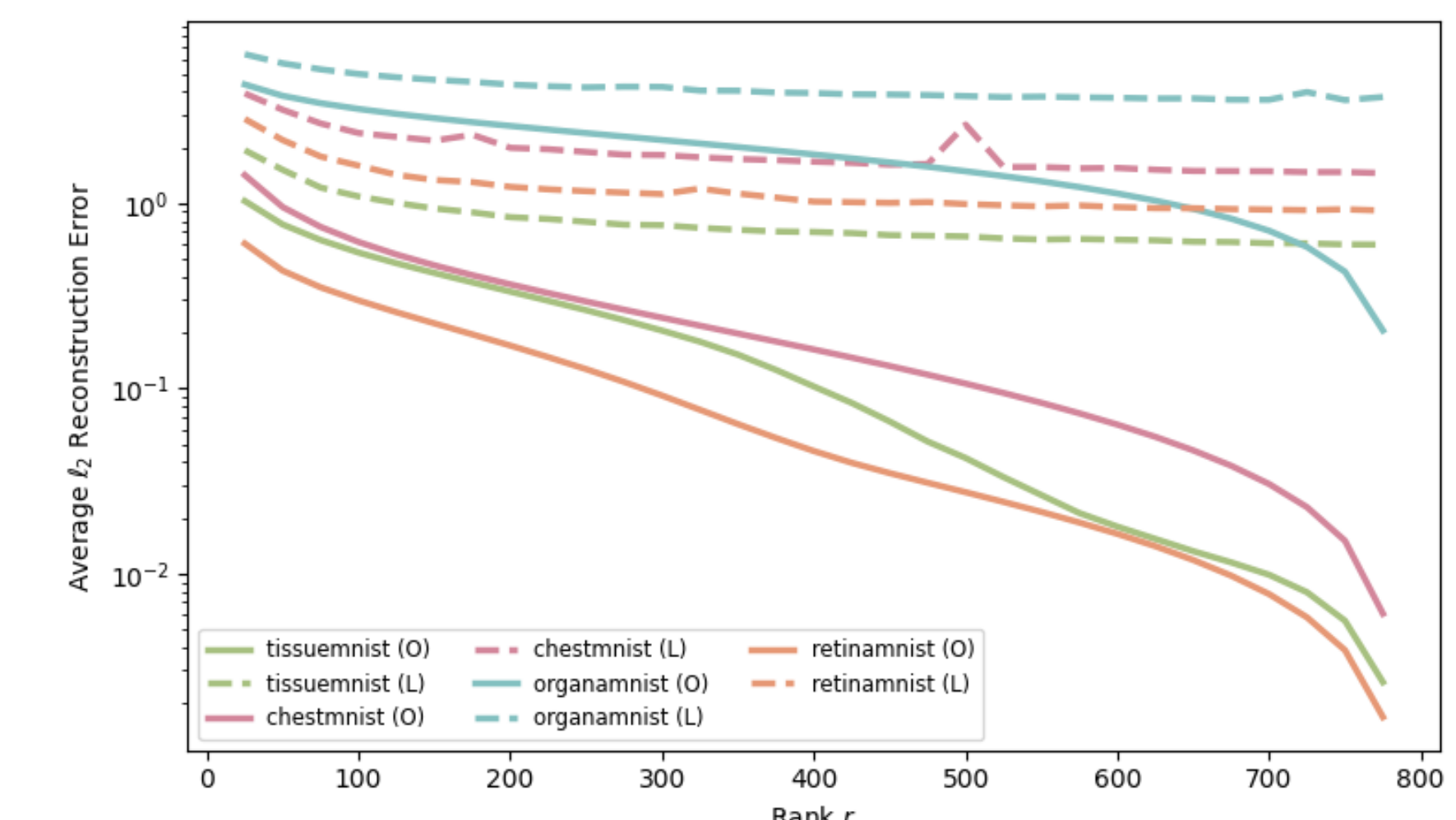
Optimal and Learned Forward and Inverse Mappings applied on ChestMNIST data with Gaussian forward operator



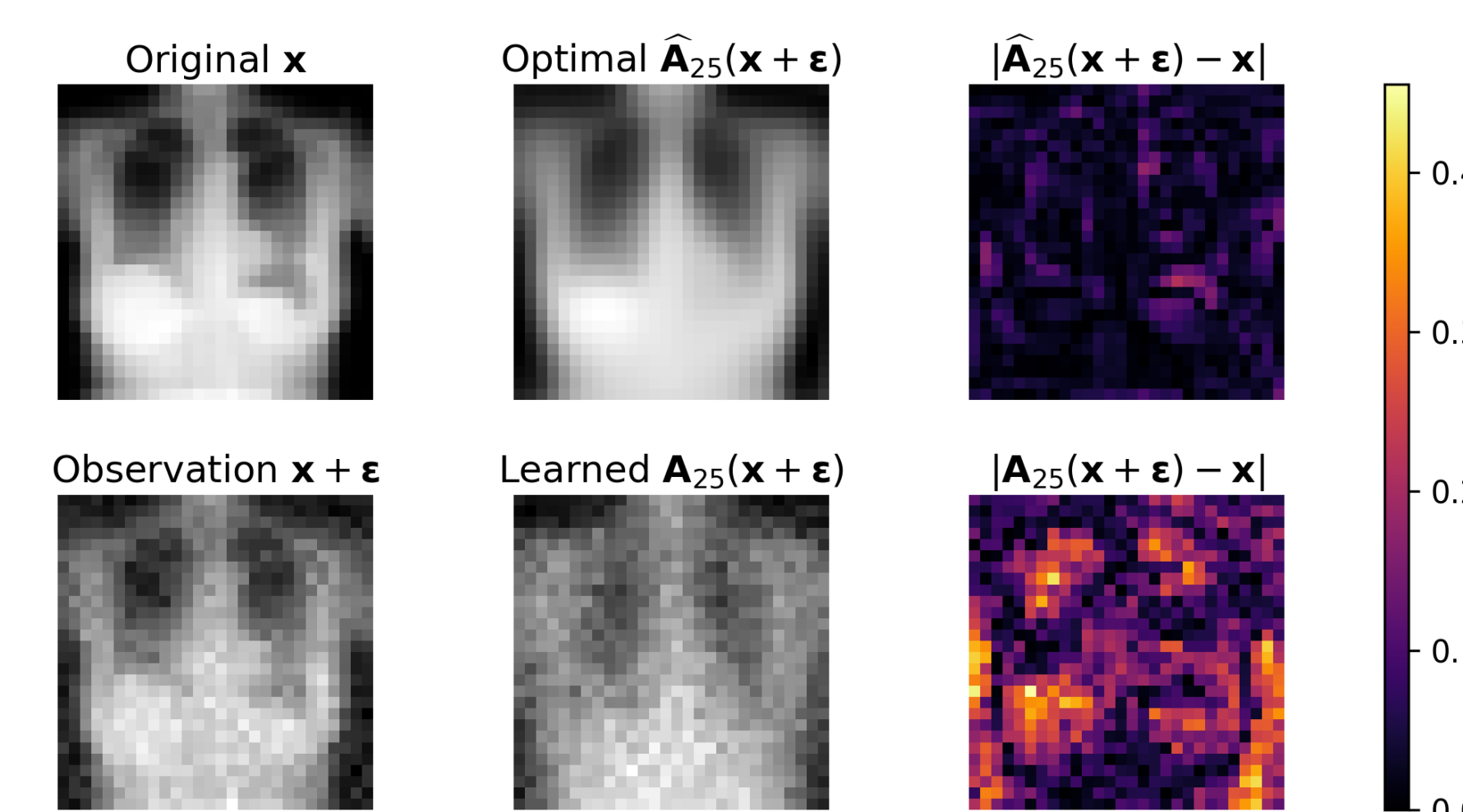
Affine Linear Autoencoder : ChestMNIST data



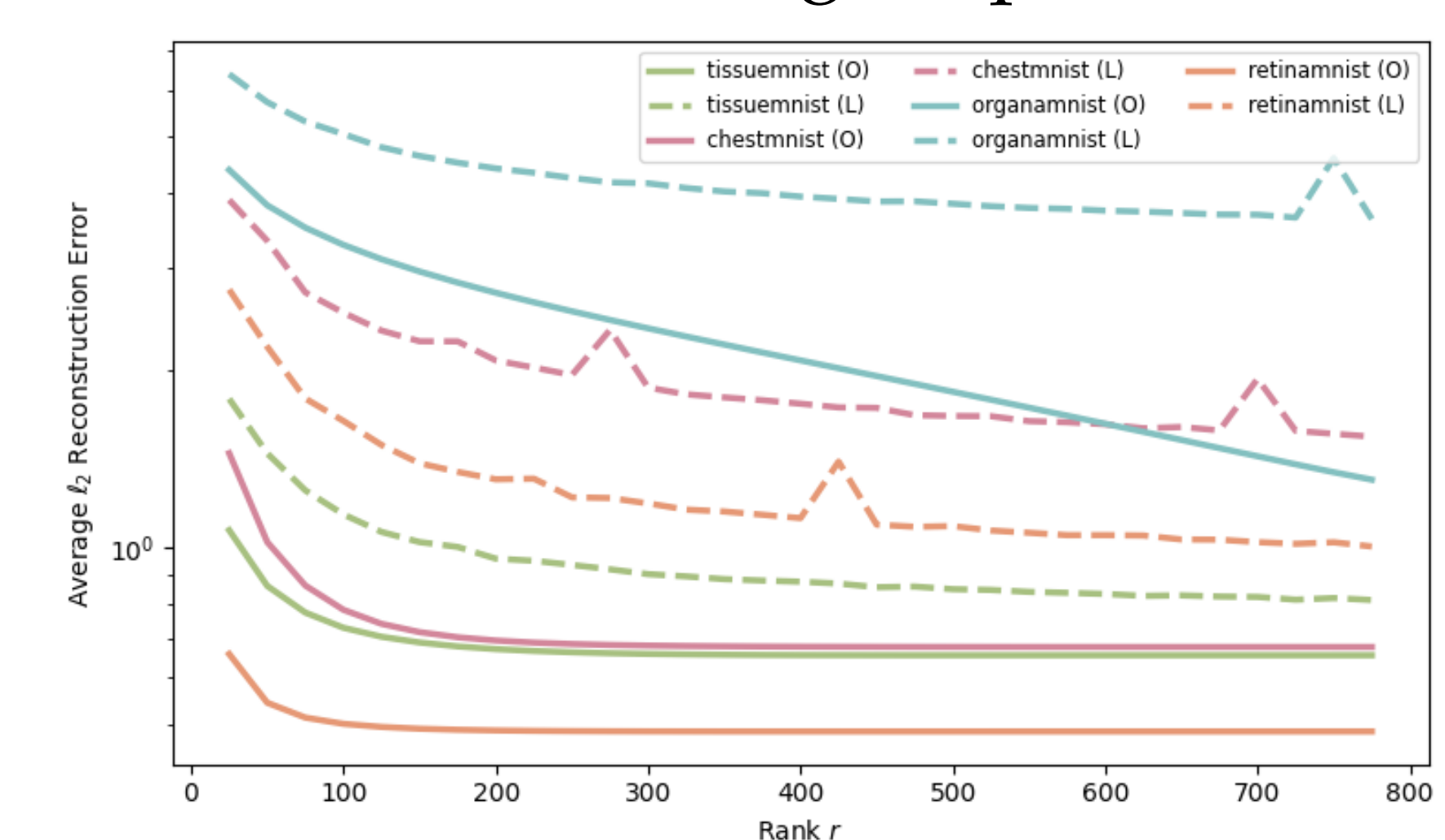
Comparing Learned vs Optimal : Affine Linear Autoencoder



Denosing Map : ChestMNIST data



Comparing Learned vs Optimal : Denosing Map



REFERENCES

- [1] Shmuel Friedland and Anatoli Torokhti. Generalized rank-constrained matrix approximations. *SIAM Journal on Matrix Analysis and Applications*, 29(2):656–659, 2007.

ANIMATIONS

Inverse End-to-End
Left: ChestMNIST
Right: RetinaMNIST

